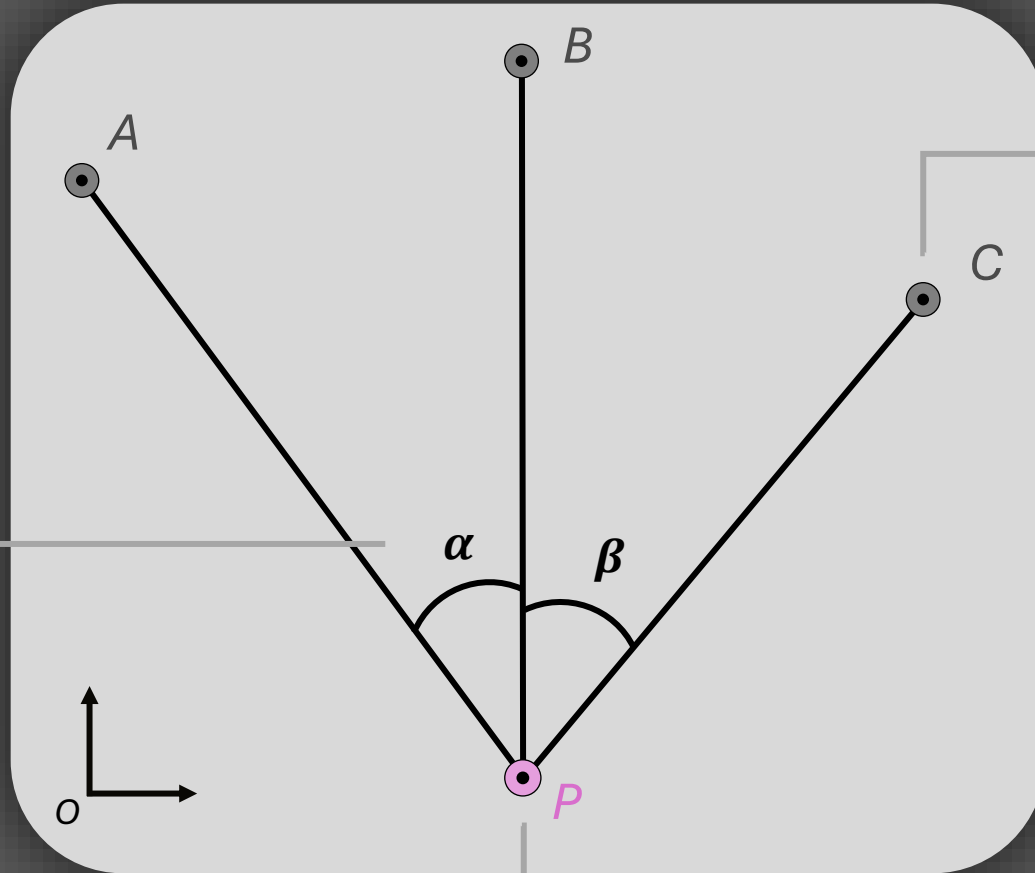




The Resection Problem



Three known points A, B and C (beacons)

Relative angular measurements α and β from P

Unknown point P (station)



Applications



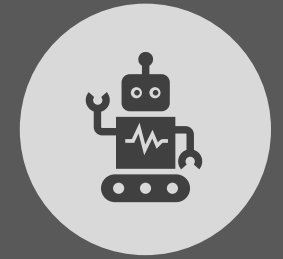
Geodesy



Navigation



**Computer
Graphics**



**Robot Path
Planning**



Applications



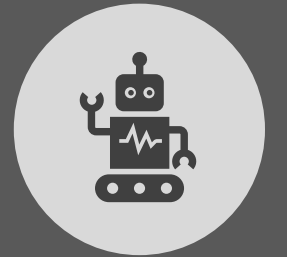
Geodesy



Navigation



**Computer
Graphics**



**Robot Path
Planning**



Applications



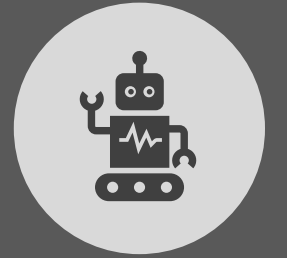
Geodesy



Navigation



**Computer
Graphics**



**Robot Path
Planning**



Applications



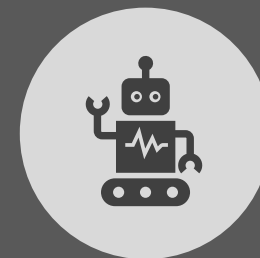
Geodesy



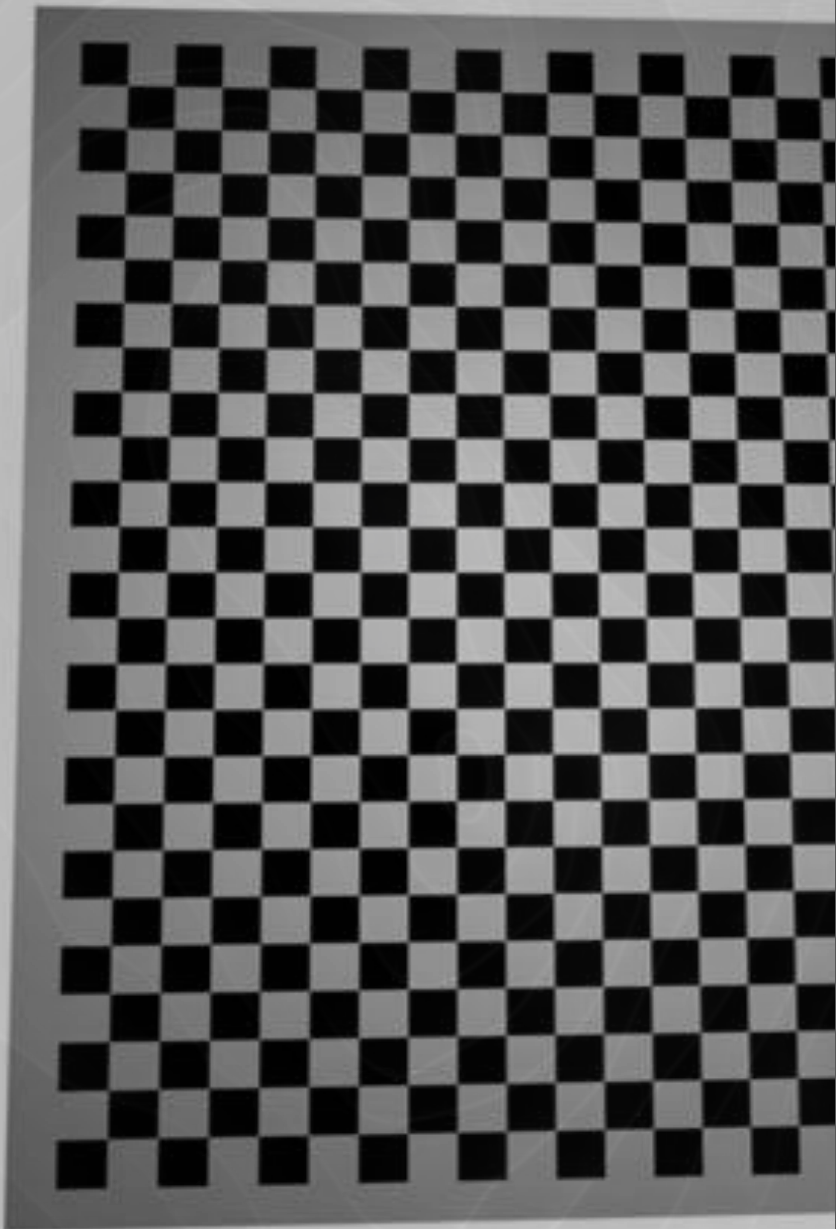
Navigation

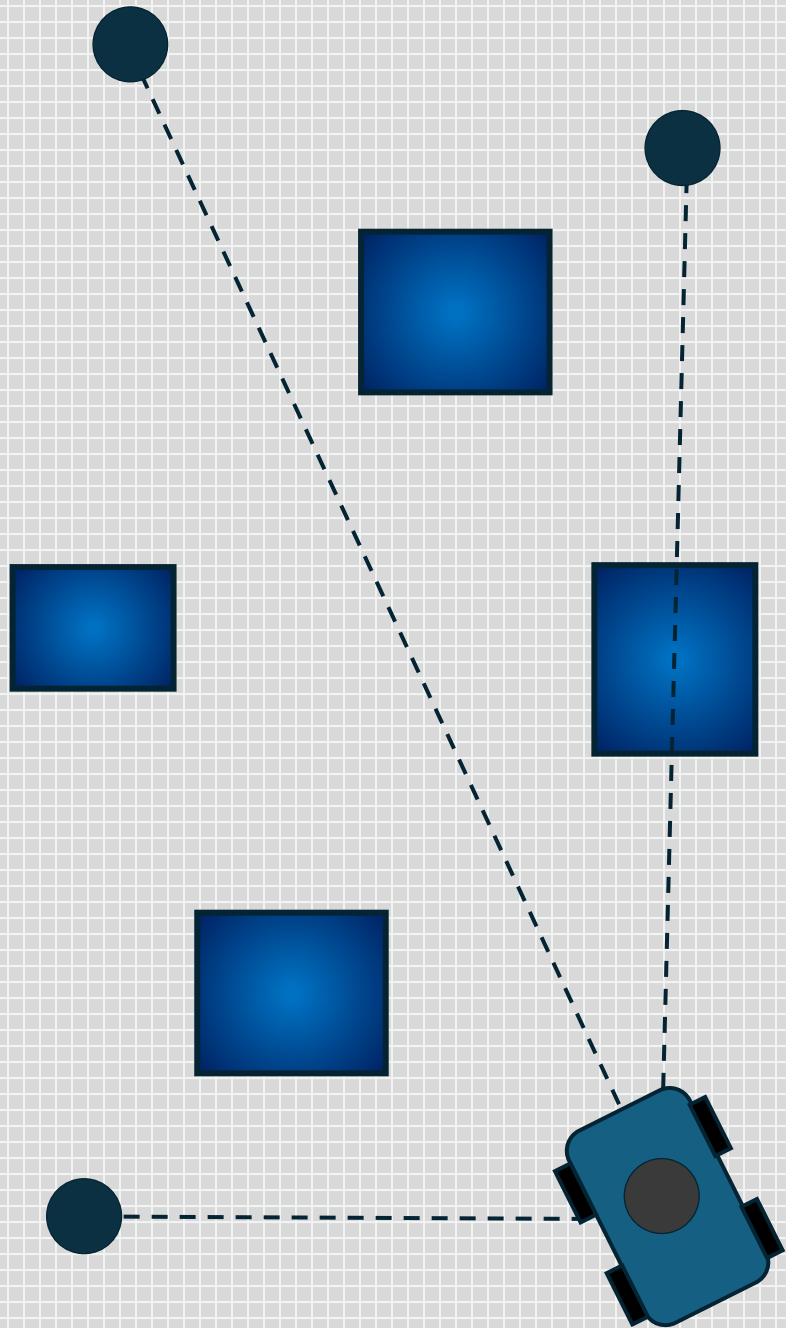


**Computer
Graphics**



**Robot Path
Planning**





Applications



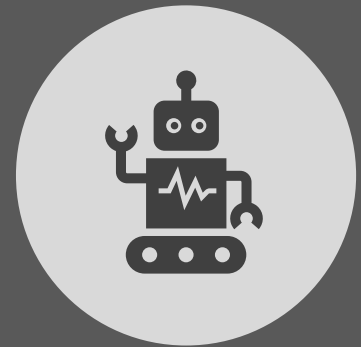
Geodesy



Navigation



**Computer
Graphics**



**Robot Path
Planning**



Tradicional Methods

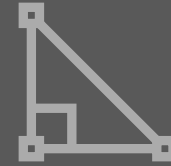


“

Traditionally, solutions to this problem have relied on heavily algebraically loaded methods, which can be complex and challenging to comprehend.

Trigonometric

Tradicional Methods



Trigonometric methods are some of the oldest and most famous procedures for solving the 2D resection problem. They are based on the use of trigonometric functions to compute the position of the observer using the angles between the known points and the observer

Snellius

Kaestner-Burkhardt

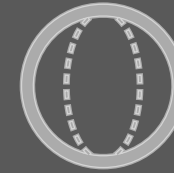
Madsen and Andersen

Easton and Cameron

Cassini

Geometric

Tradicional Methods



Geometric methods use geometrical constructions and properties of the known points to calculate the position of the observer. These methods are based on the use of geometric and graphic principles to solve the problem.

Collins

McGillem

Cohen and Koss

Esteves et al.

Tsukiyama

Font-Llagunes

Ligas

Pierlot et al.

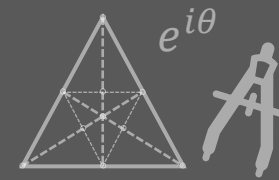
Cassini



Iterative methods use iterative algorithms to converge to the observer position. These methods are based on the use of an initial estimate of the observer position, which is refined iteratively until convergence is achieved.

Sanchiz et al.

Dekov



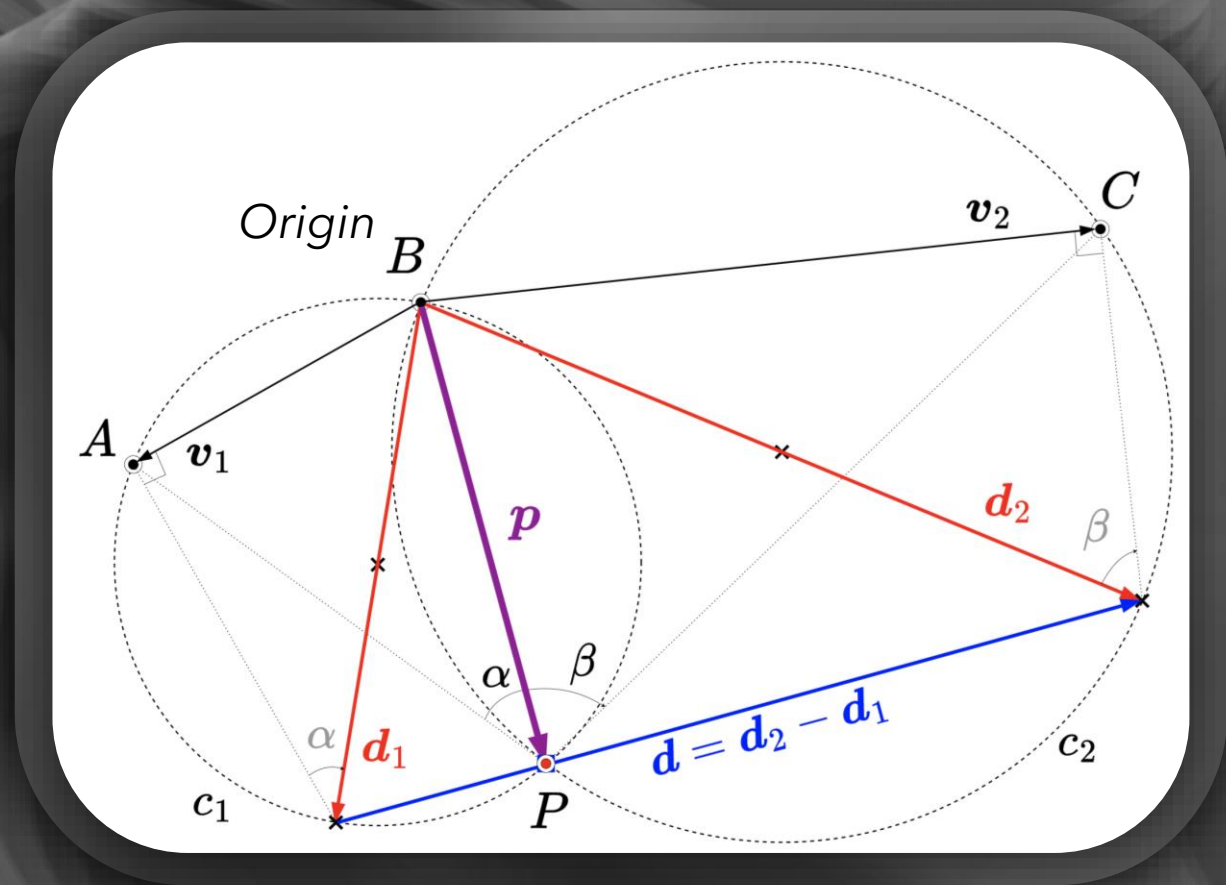
There are other methods that do not fit in with the above. For example, based on barycentric coordinates, complex numbers or graphical methods.

Collins

Willerding

Tienstra

Resection using Geometric Algebra



Resection using Geometric Algebra

Compass Ruler Algebra Methods

Cassini Construction

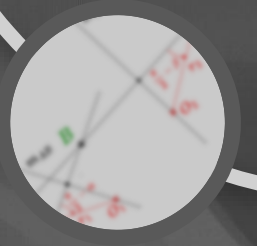
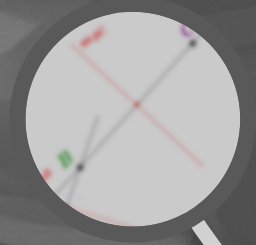
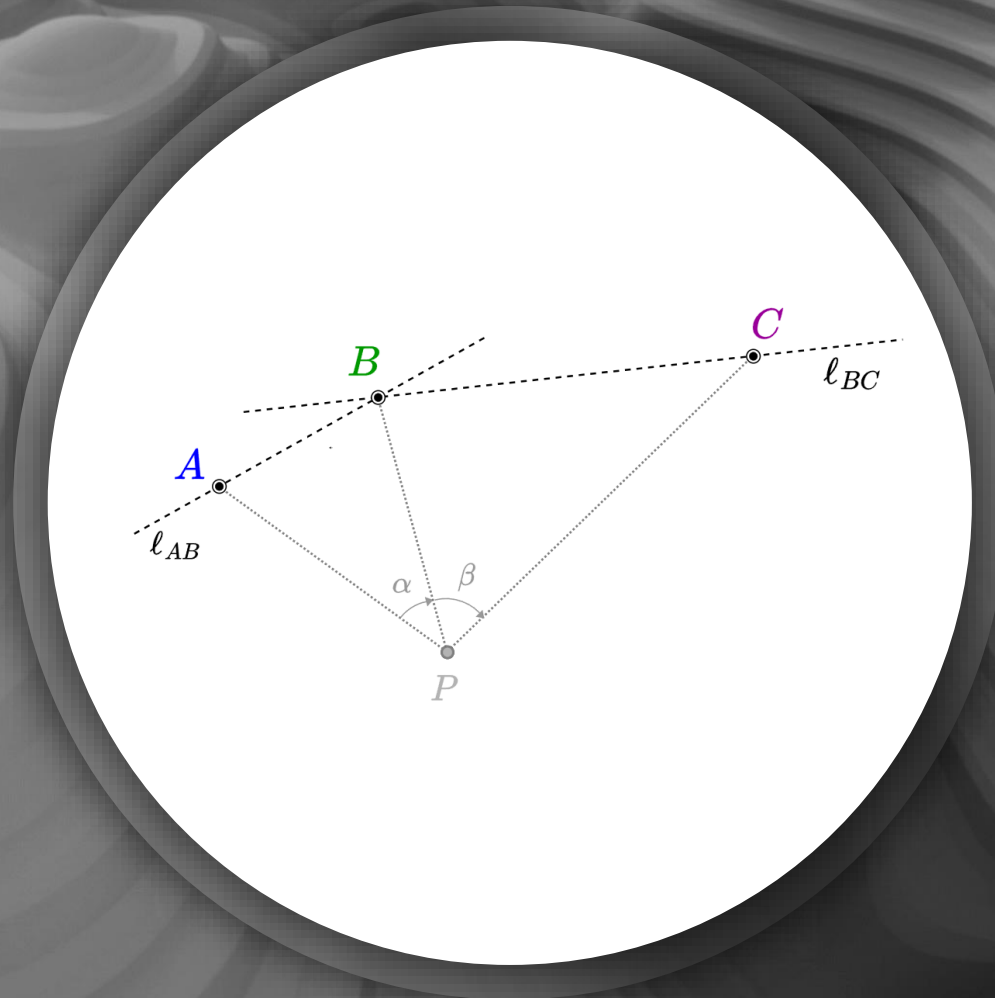
The Cassini method provides a solution to the resection problem by leveraging the inscribed angle theorem.



Resection using Geometric Algebra

Compass Ruler Algebra Methods

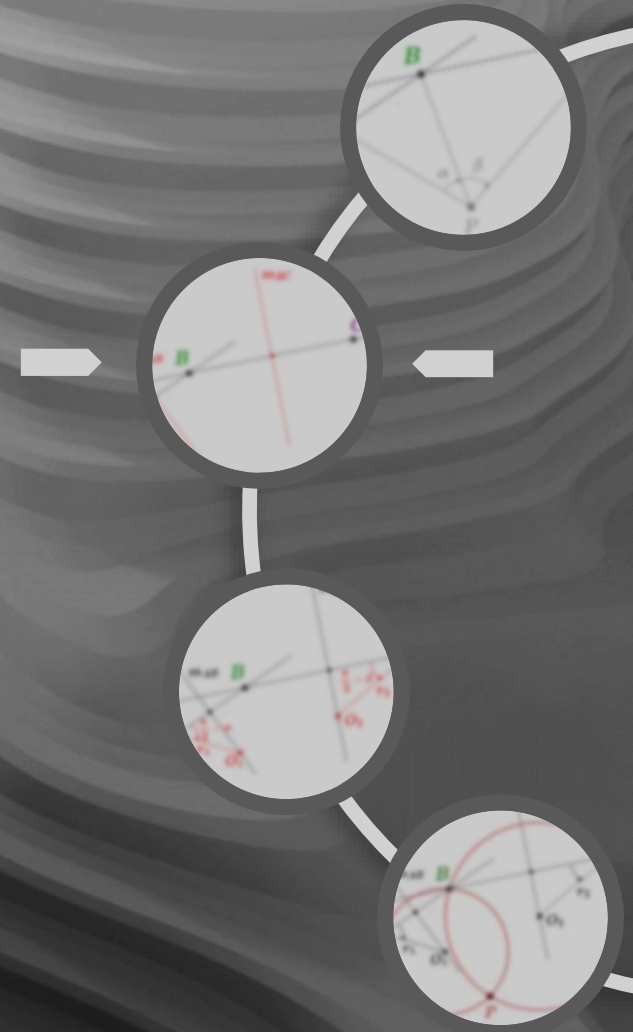
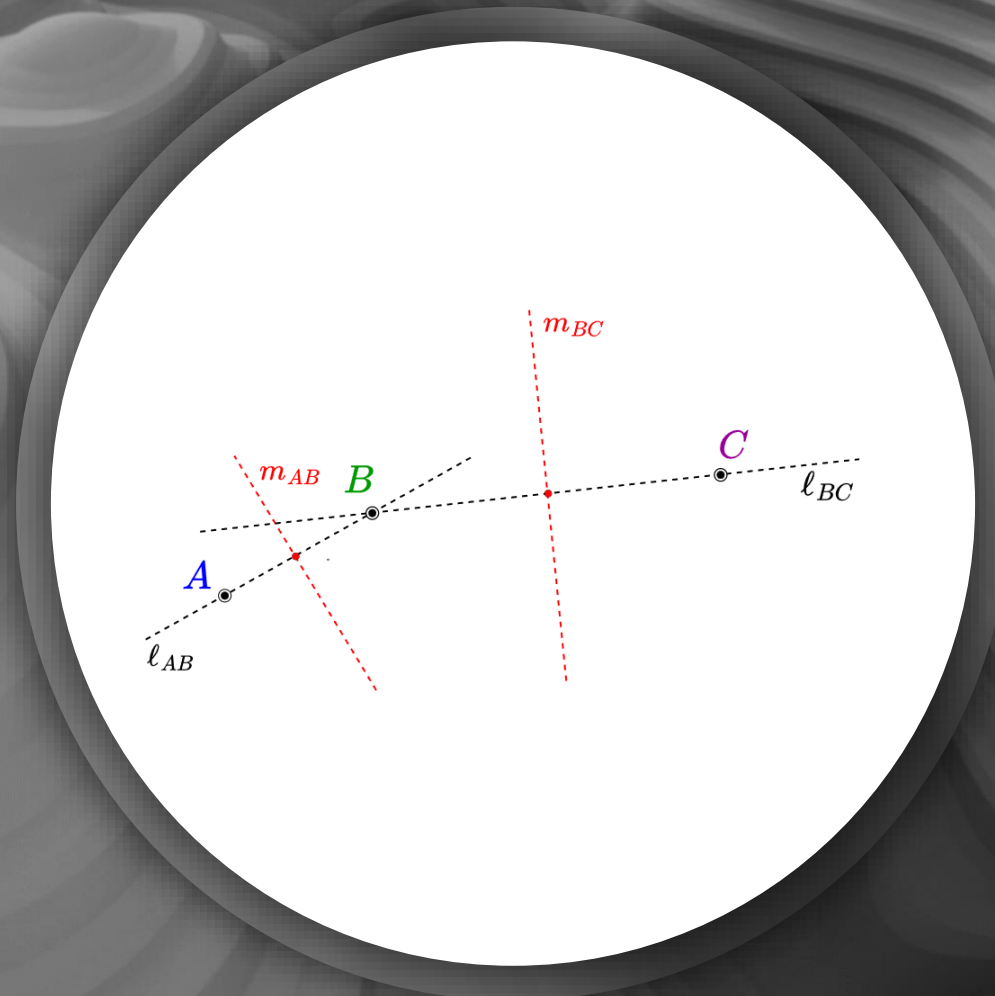
Cassini Construction



Resection using Geometric Algebra

Compass Ruler Algebra Methods

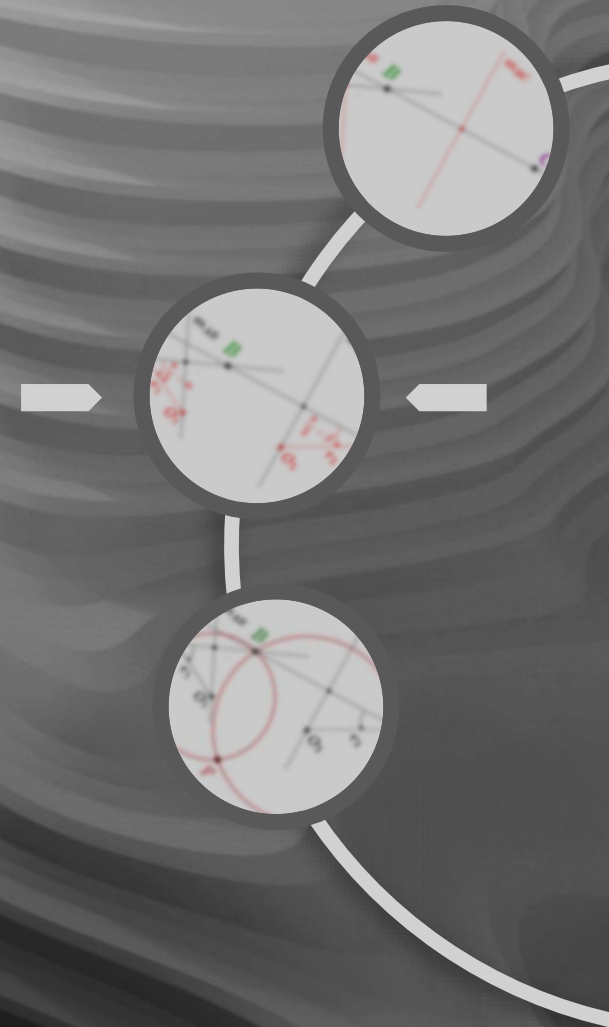
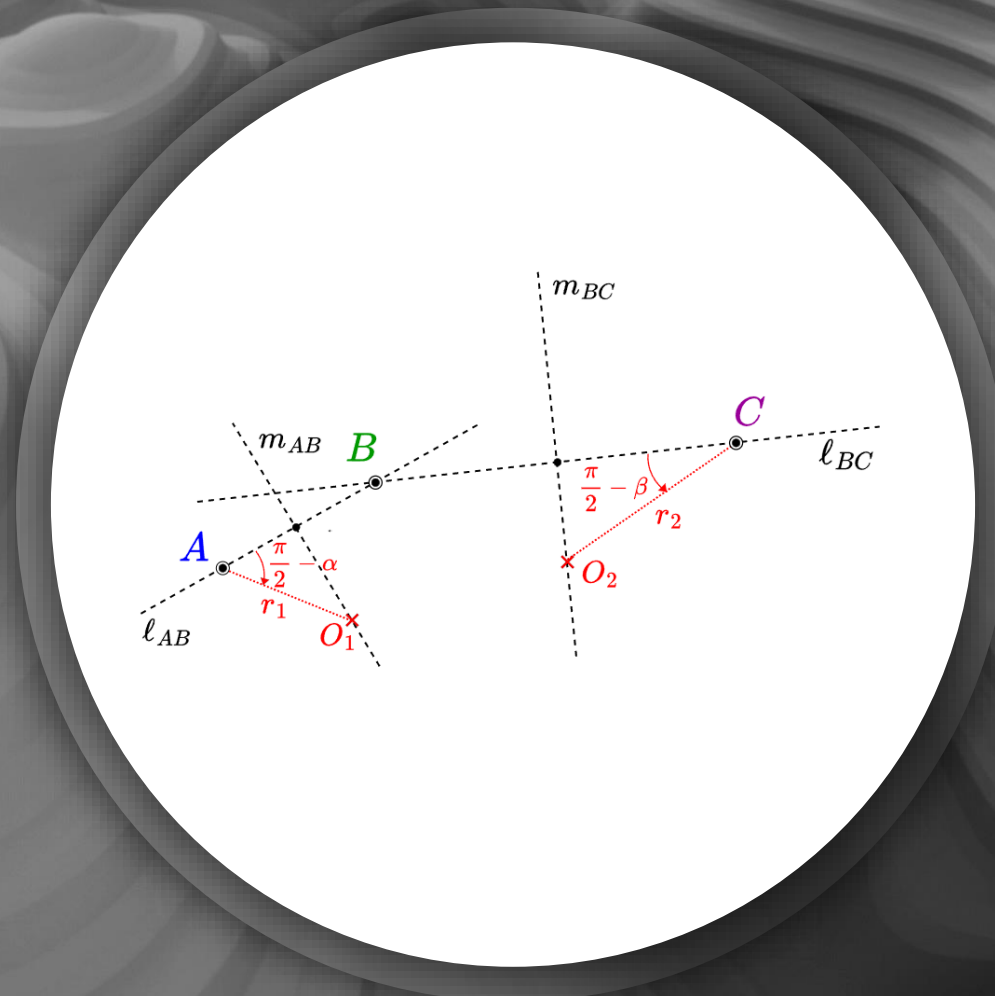
Cassini Construction



Resection using Geometric Algebra

Compass Ruler Algebra Methods

Cassini Construction



Resection using Geometric Algebra

Compass Ruler Algebra Methods

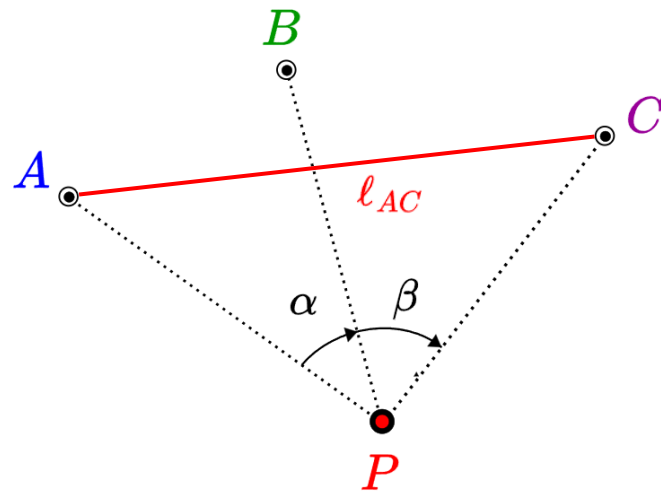
Collins Construction

The graphical method of Collins provides a solution using the intersection of the line passing through the point B and the so-called Collins auxiliary point E with the circle containing the points A, C and E.

Resection using Geometric Algebra

Compass Ruler Algebra Methods

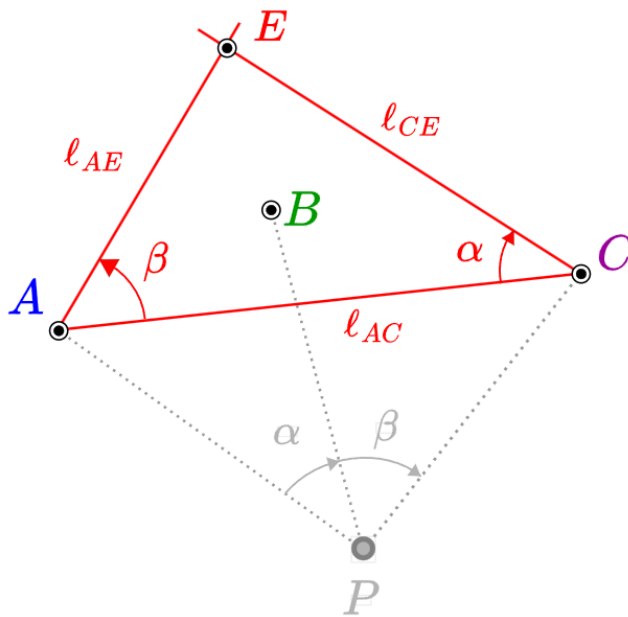
Collins Construction



Resection using Geometric Algebra

Compass Ruler Algebra Methods

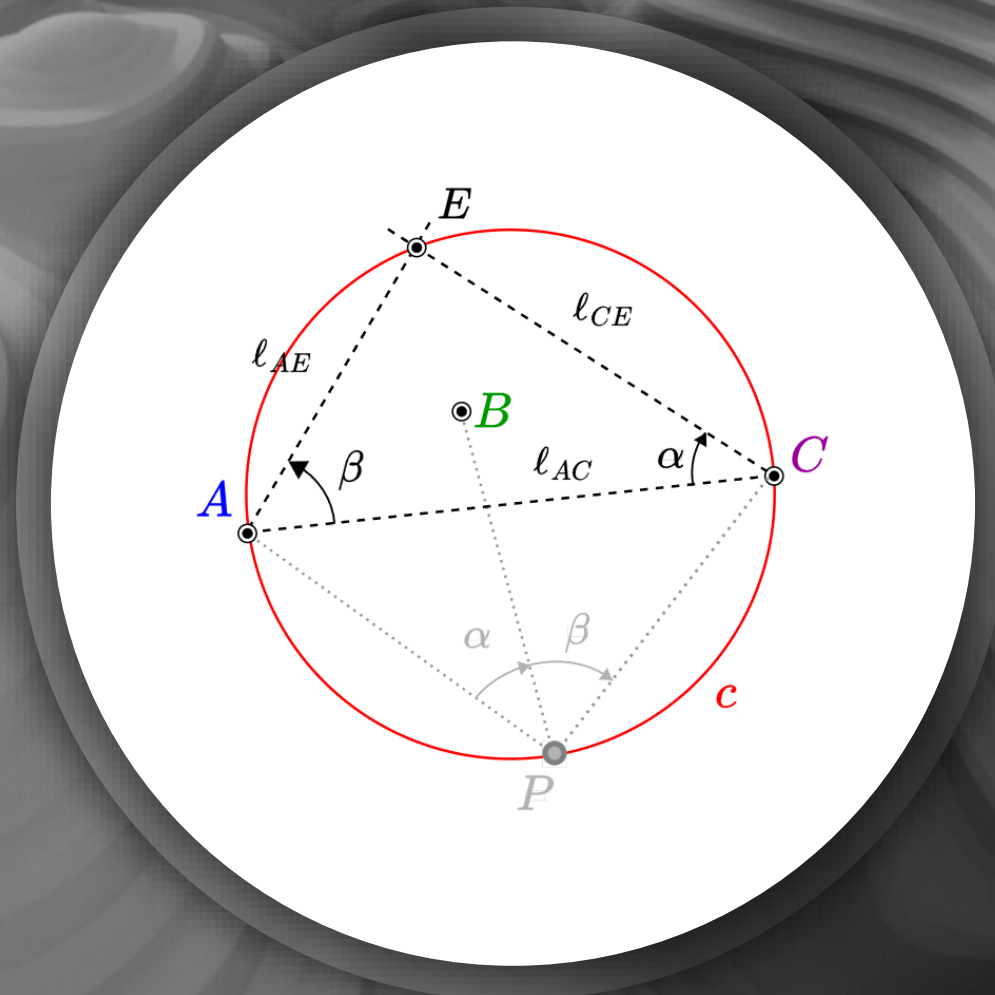
Collins Construction



Resection using Geometric Algebra

Compass Ruler Algebra Methods

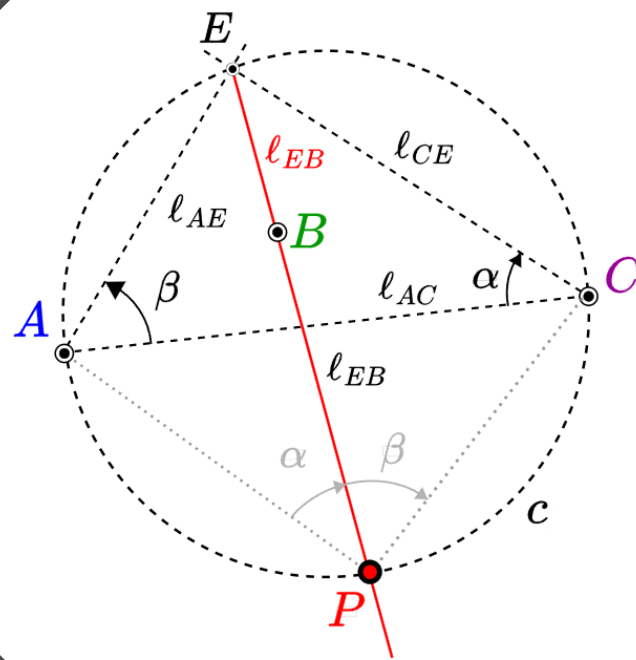
Collins Construction



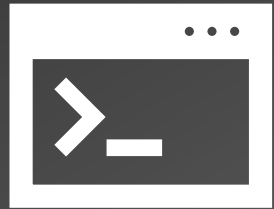
Resection using Geometric Algebra

Compass Ruler Algebra Methods

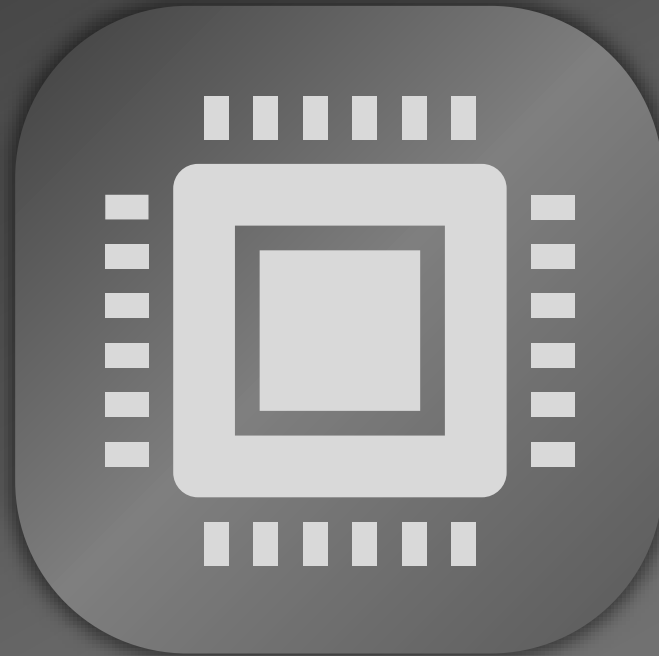
Collins Construction



Benchmarks



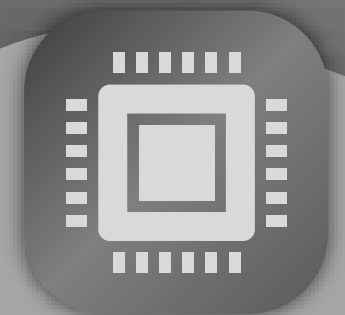
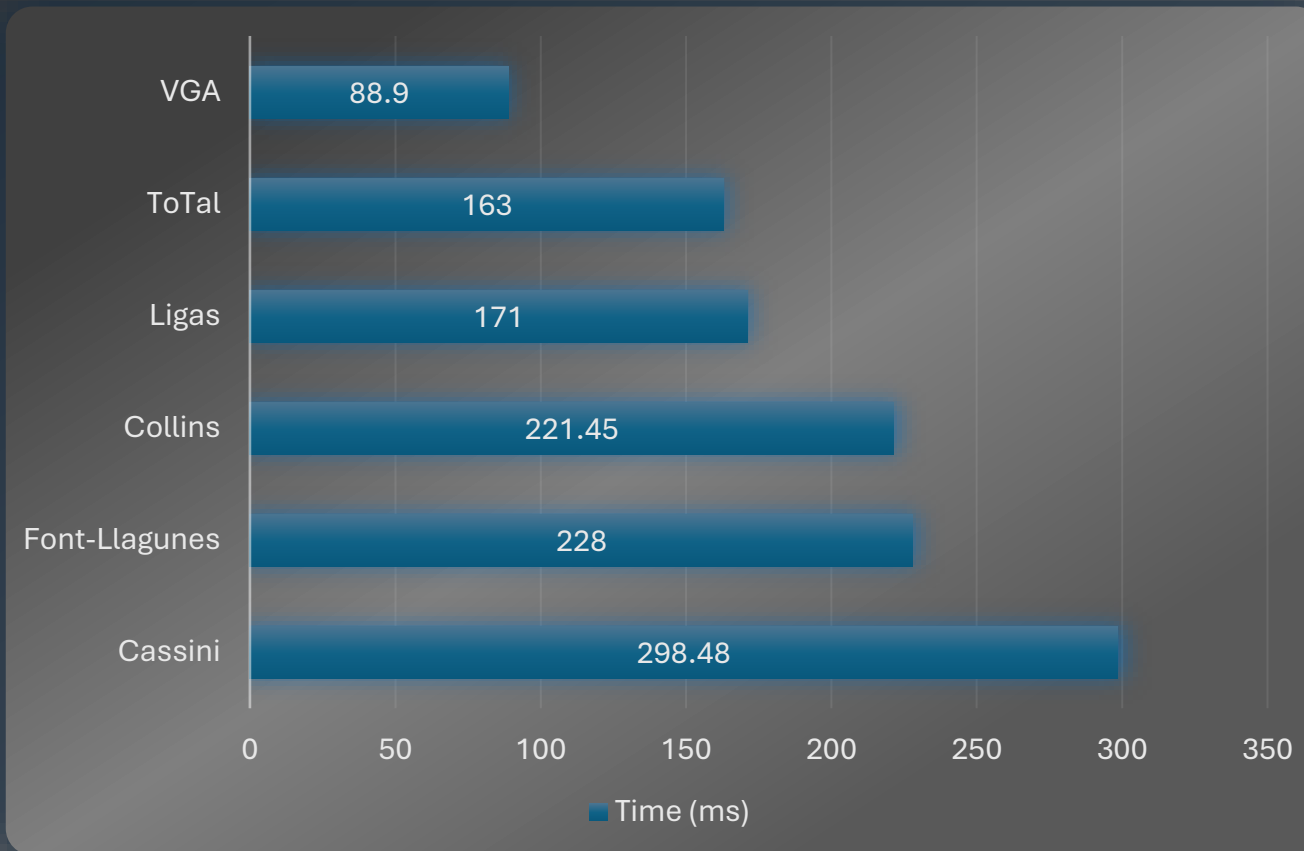
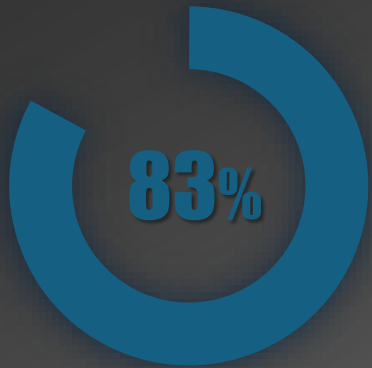
C#



**GA-FuL
library**

A comprehensive set of benchmarks was conducted, comparing our algorithms against top-efficient. Each algorithm was executed 10^6 times at random locations.

Benchmarks

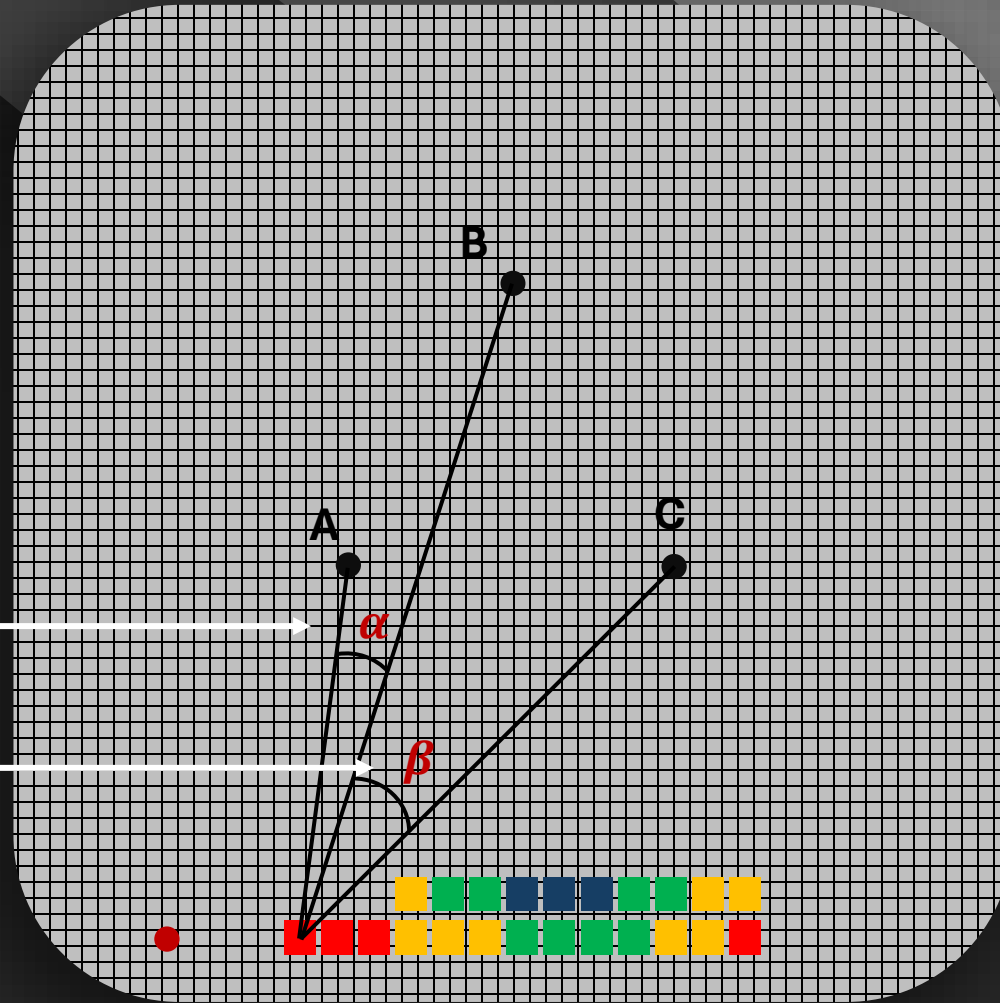


Uncertainty analysis

Gaussian noise



4 m

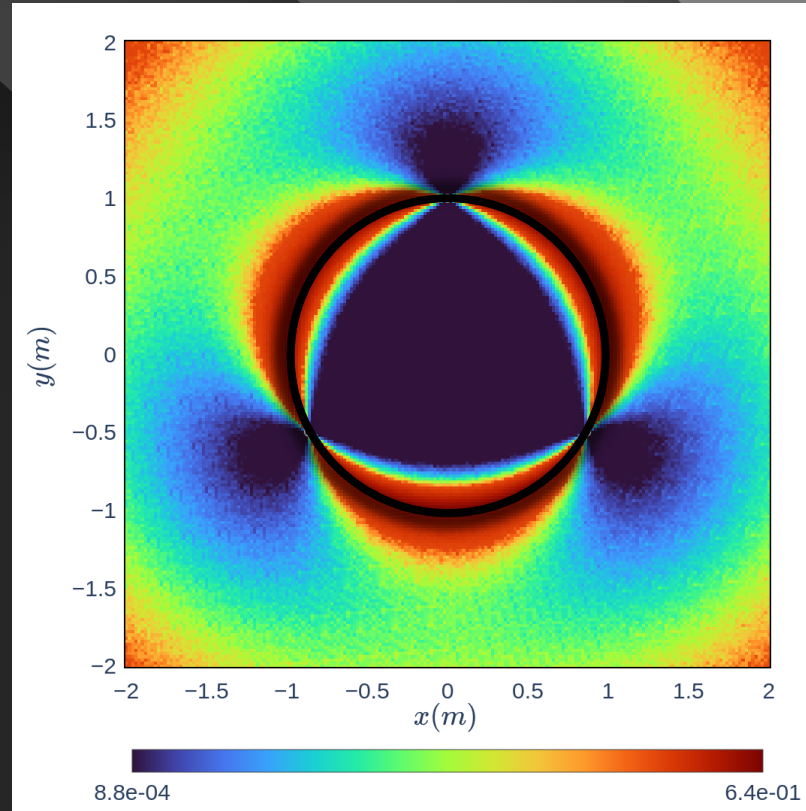
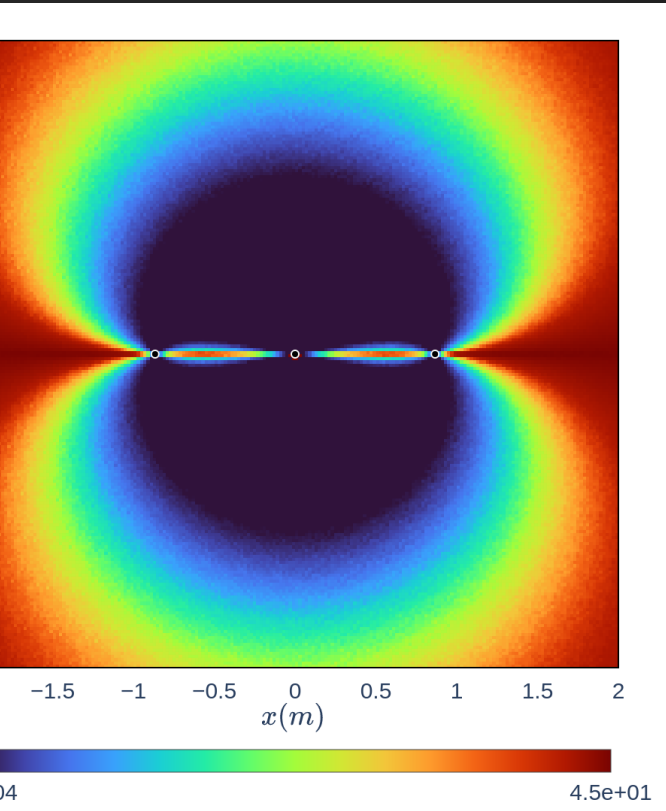


4 m



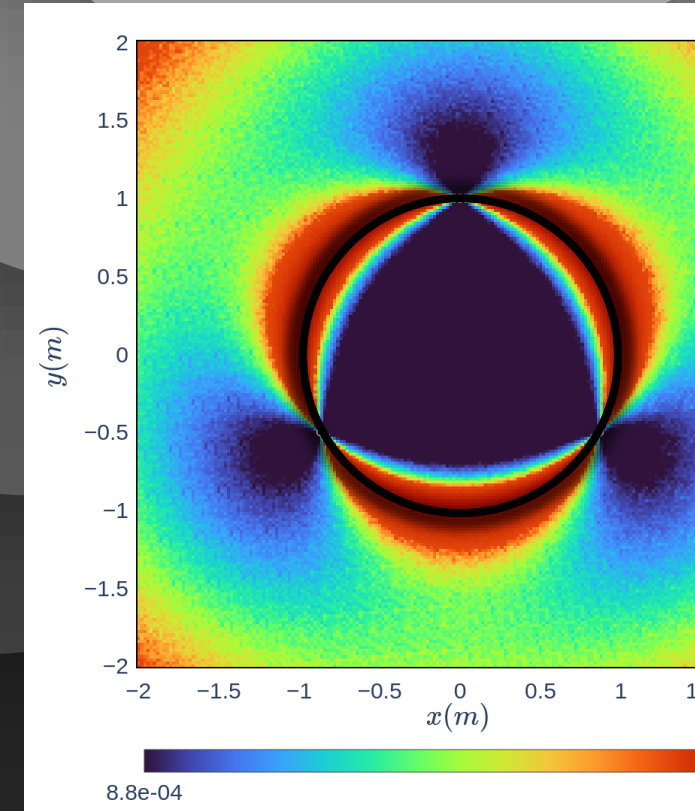
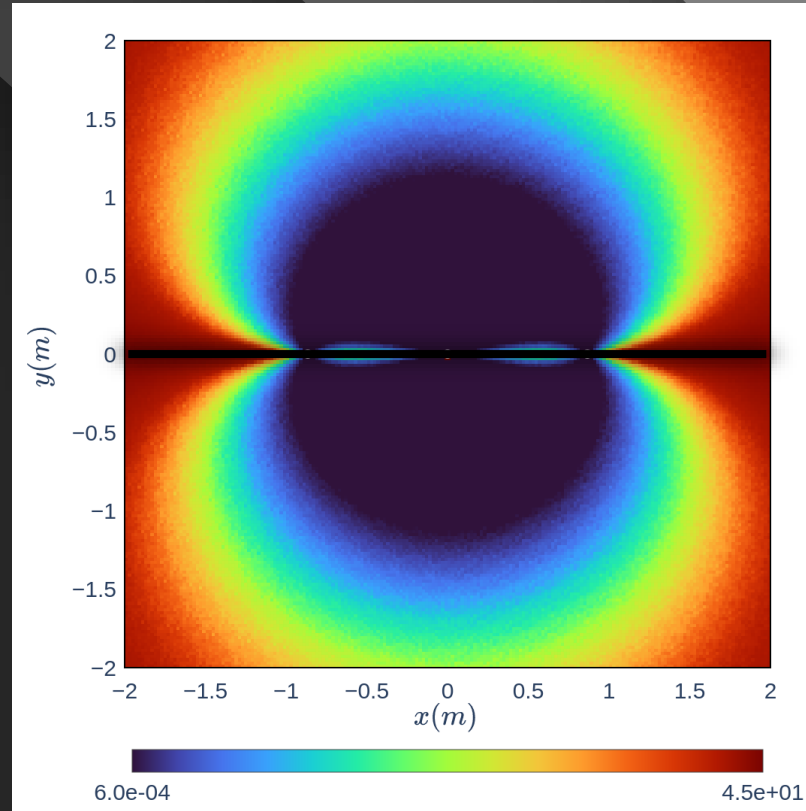
2 cm

Uncertainty analysis



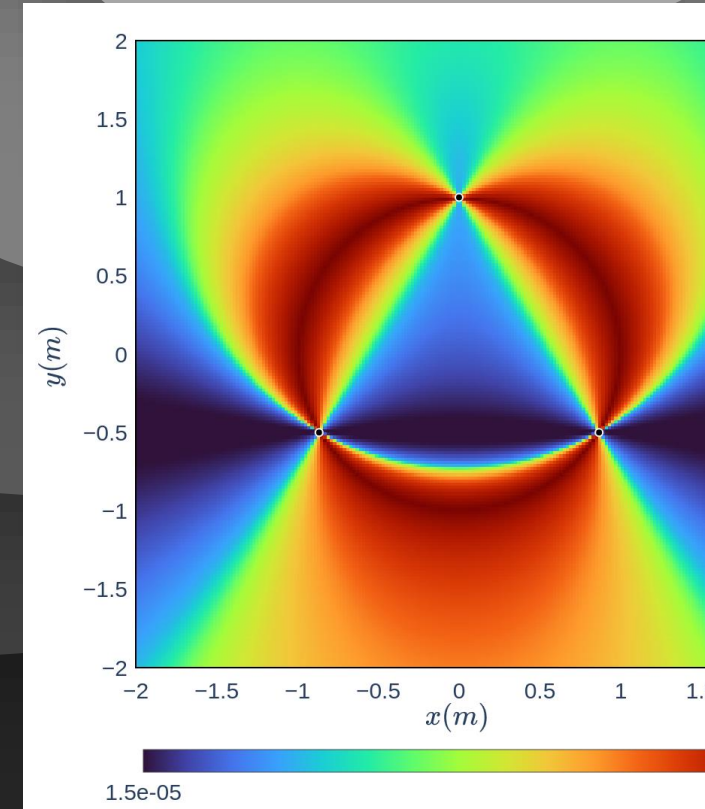
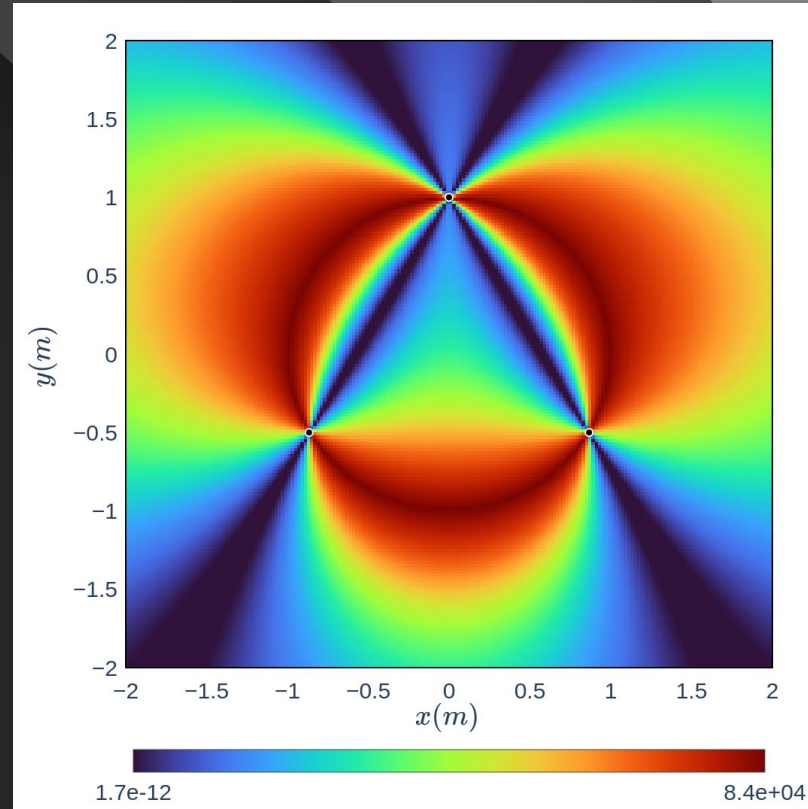
Equilateral
Triangle

Uncertainty analysis



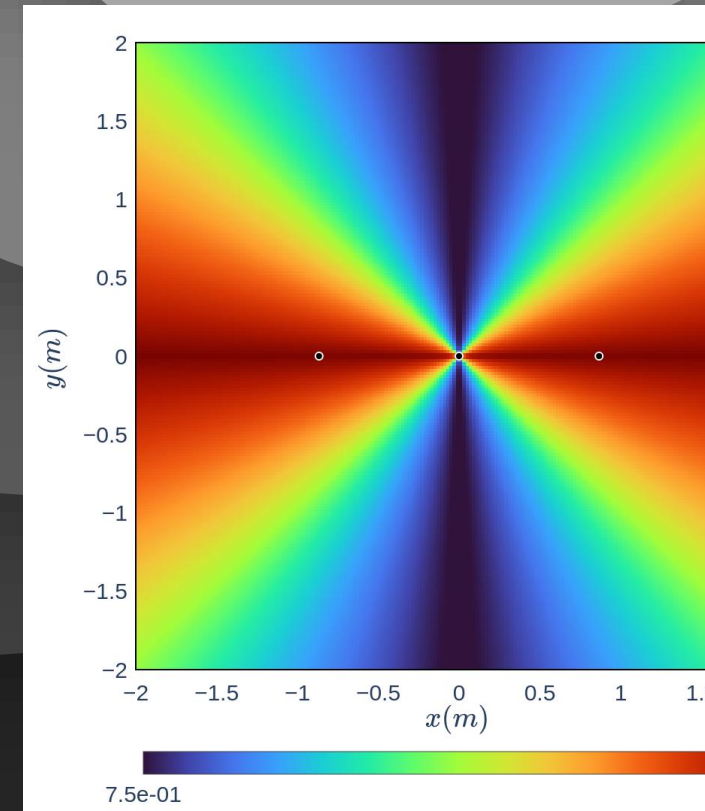
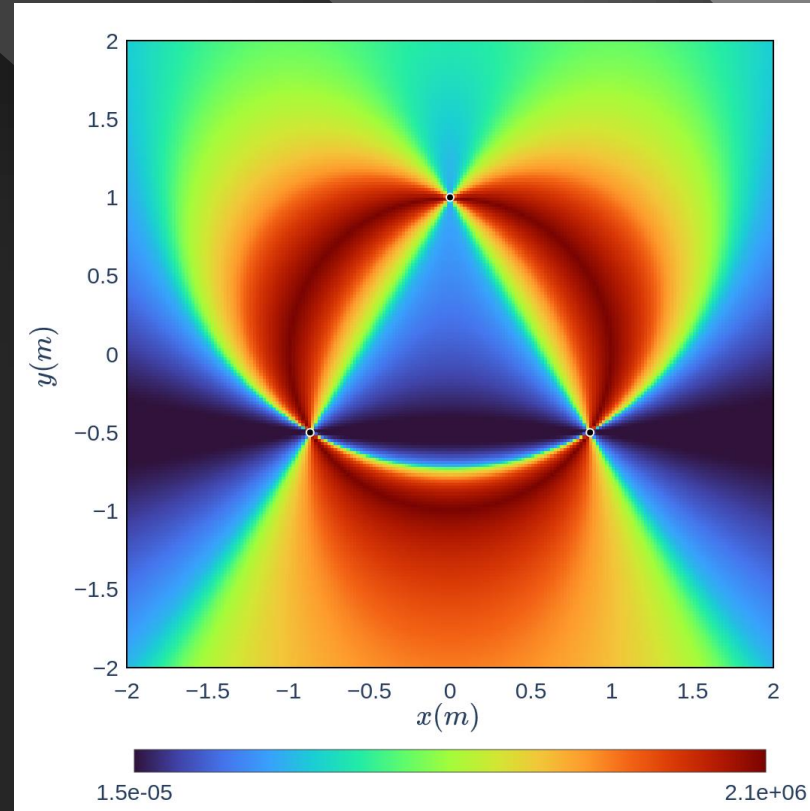
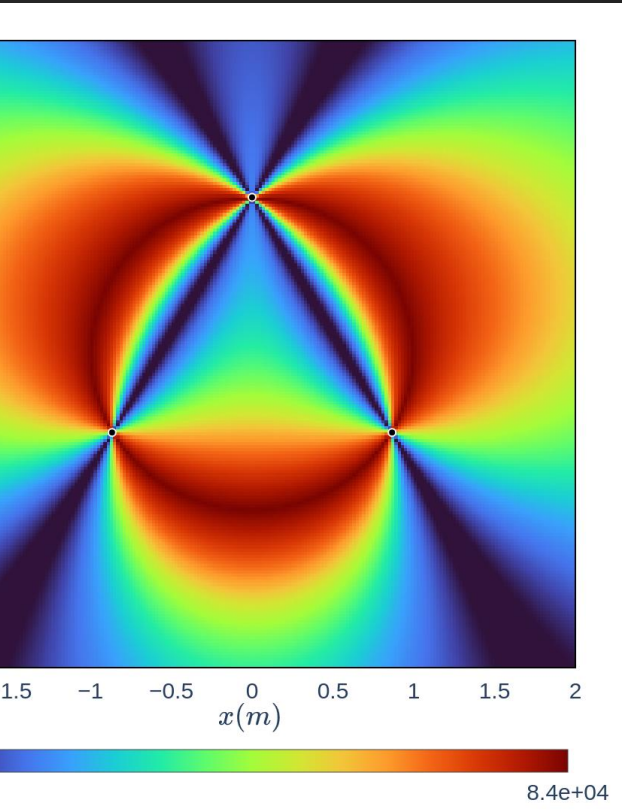
Colinear

Uncertainty analysis



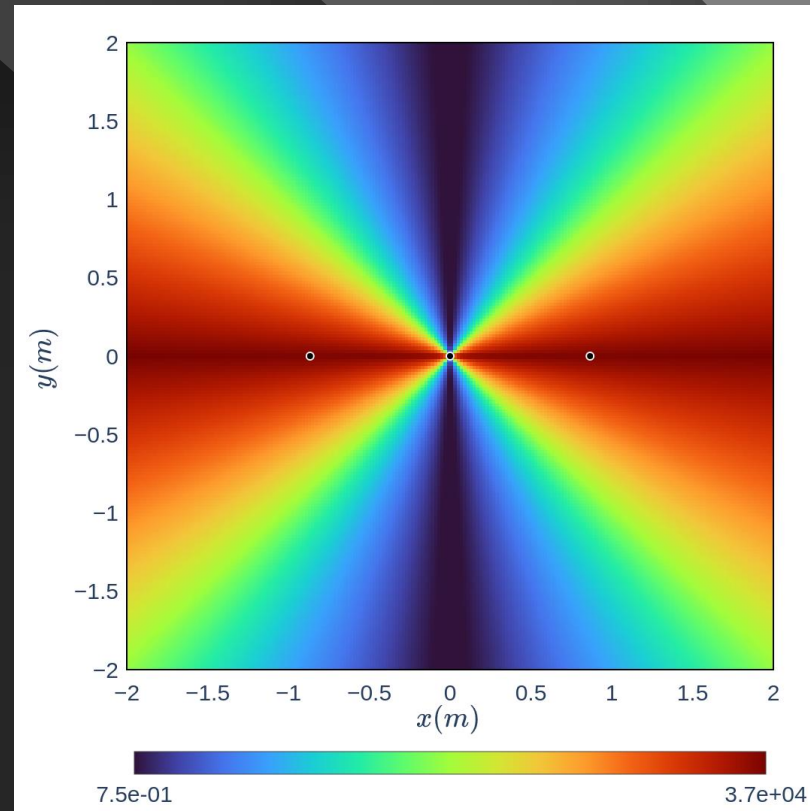
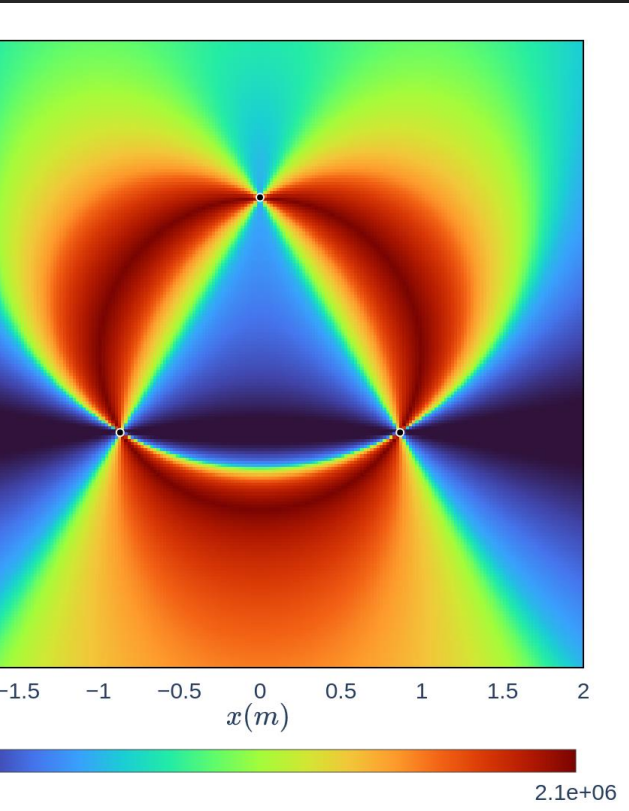
VGA Method
 $D = d^2$

Uncertainty analysis



Collins Method
 $D = -2(\mathbf{e} \cdot \mathbf{b})$

Uncertainty analysis



Cassini Method
 $D = -2(o_1 \cdot o_2)$

CONCLUSIONS

This article introduces a novel method for solving the two-dimensional resection problem using conformal geometric algebra (CGA). The CGA approach simplifies the problem by avoiding complex algebraic manipulations and coordinate transformations, offering a more intuitive and efficient solution. Numerical simulations confirm the method's accuracy and efficiency, suggesting its potential applications in fields like surveying, geodesy, computer graphics, robotics, and navigation.



Thank you

Any questions?