

Mobile
Landmark
Recognition

Introduction

Approach
takenComputer
Vision part

J2ME

Conclusion

MOBILE LANDMARK RECOGNITION

WORKING TITLE - POIRE: POINT OF INTEREST RECOGNITION

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DOAS Progress Meeting



SHORT PROJECT DESCRIPTION

- Landmark recognition;
- Computer Vision is done on local device;
- Approximate location is known:
set of objects is small.

LIMITED HARDWARE

We can't use computationally expensive algorithms

- Photos can't be stored in a database, only a symbolic representation;
- Only machine learning algorithms which have a easy to calculate decision boundary.

NO LAB CIRCUMSTANCES

- Different lightning conditions;
- Rotation/translation/scaling;
- Different cameras.

TWO SUB-PROBLEMS

- Getting familiar with J2ME;
- Creating a computer vision application which satisfies our demands.

TWO MAJOR APPROACHES

- Use features which are robust;
- Find a representation of images which is robust.

POSSIBLE FEATURES

- Skyline detection combined with a descriptor (fft, distance between corners);
- Features of straight lines within an image (orientation, length, color pairs on either side);
- Corner features (location, angle etc.);
- Color histograms;
- Clusters in a colorspace (i.e. HVC).

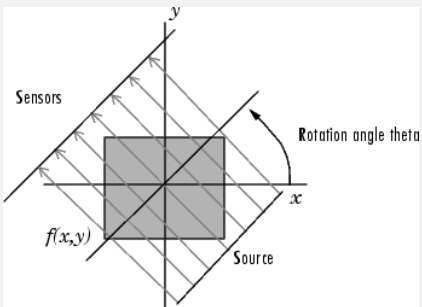
FINDING A ROBUST REPRESENTATION

- Problem is hard because of extrinsic variation;
- So: find a way to neutralize this variation;
- Many possibilities...
- Example: Möbius-Radon transformation.

EXAMPLE: MÖBIUS-RADON TRANSFORMATION

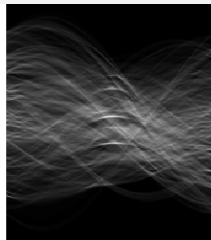
Steps:

- Obtain edge image
- Apply Radon transformation:



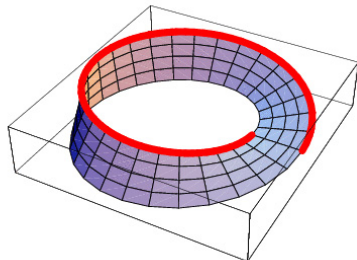
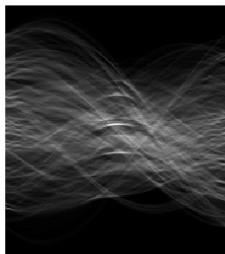
EXAMPLE: MÖBIUS-RADON TRANSFORMATION

So we have:



EXAMPLE: MÖBIUS-RADON TRANSFORMATION

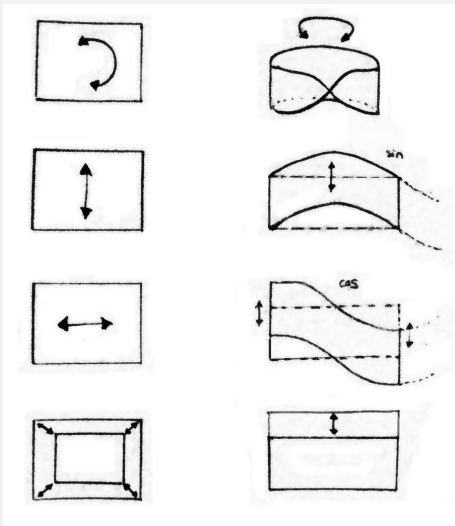
- Now connect $\theta = 180$ and $\theta = 0$
- And 'normalize' by shifting important lines to $\theta = 0$.



EXAMPLE: MÖBIUS-RADON TRANSFORMATION

- The shift over the Möbius ring corrects for rotation;
- For other corrections, things aren't so easy.

EXAMPLE: MÖBIUS-RADON TRANSFORMATION



CURRENT SITUATION ON MOBILE PHONES

- Lots of image retrieval systems;
- There exists an open source computer vision library for Symbian (cpp). Drawback: support on a limited number of phones;
- We have chosen J2ME because of its widespread availability.

JAVA 2 MOBILE EDITION

- We've built an application which takes a picture and we're able to manipulate that image;
- We're now designing a small computer vision library which supports the most basic computer vision algorithms.

WHAT REMAINS TO BE DONE

- Experiment with features; choose final set;
- Decide upon learning algorithm;
- Implement J2ME feature extraction methods;
- Develop real-world test environment.