# UvA Matching 2017: Problem Solving with Prolog (BSc KI) 

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## Plan for this Module

- Big picture:
- What is Artificial Intelligence (AI)?
- What is problem solving and why is it so central to AI?
- How can logic programming help?
- And then for the actual topic of this lecture:
- Strategies for solving Towers of Hanoi
- Implementing those strategies in (simplified!) Prolog


## Artificial Intelligence

What is AI? People do not agree on how to answer this.
My favourite answer:
AI is whatever AI researchers do.
This is true, but not helpful to you right now. So maybe this:

> AI is about getting machines to perform tasks that we tend to associate with "intelligence" when performed by humans.

More specifically:

- no need for the machine to be intelligent (philosophy)
- no need to agree what "intelligence" is exactly (psychology)
- no need to focus only on things humans are good at


## Problem Solving

AI is about getting machines to perform tasks ...
At the core of such (possibly physical) tasks there often are rather abstract problems we need to solve. A solution often requires us to find a sequence of actions to achieve a given goal:

- finding a path from $A$ to $B$ on a street map
- computing a sequence of electronic signals for a robot to do $X$
- solving Rubik's Cube



## Logic Programming

Prolog is a programming language that is particularly useful for problem solving. It is based on an idea called logic programming.


## Towers of Hanoi

Move all disks from the leftmost to the rightmost peg, whilst:

- moving only one disk at a time, and
- never placing a disk on top of a smaller disk



## Problem Representation

We don't want to build a robot that can physically move the disks (not today, anyway). We just want to find a general method that tells us in which order to move the disks.


First, we need to find an appropriate level of representation ...

## Graphical Representation

| 11 | 11 | 11 |
| :---: | :---: | :---: |
| 11 | 11 | 11 |
| 11 | 1 \| | 11 |
| xxxxxxxxxxx | 1 | 1 |
| xxxxxxxxxxxxx | 11 | 1 |
| xxxxxxxxxxxxxxx | 11 | 11 |
| xxxxxxxxxxxxxxxxx | 11 | 1 |
| mxxxxxxxxxxxxxxxxxx | 11 | xxxxxxx |
| Xxxxxxxxxxxxxxxxxxxxx | \| | | Xxxxxxxxx |



1
2
3

## Prolog-internal Representation

Game $=[[3,4,5,6,7,8,9],[9],[1,2,9]]$

## Representation in Terms of Bits

```
01001010 11010010 11101010 0010111 10100101 00101010
11101010 00101100 00001000 1101010 11010101 11010101
0 0 1 0 1 0 1 0 0 1 0 1 1 1 0 1 1 1 0 1 0 1 0 1 ~ 0 0 1 0 1 0 1 ~ 1 0 1 0 0 1 1 0 ~ 1 0 1 0 0 1 0 0
0 0 1 0 1 0 1 1 1 0 1 0 0 1 1 1 ~ 0 1 0 1 1 1 1 1 ~ 1 0 1 0 0 1 0 ~ 1 0 1 0 1 1 1 0 ~ 1 0 1 0 1 1 1 0
10000010 10101000 00101010 0001101 11010010 00001011
0 0 0 1 0 1 0 0 1 0 0 0 1 0 0 1 1 1 1 0 1 0 0 0 ~ 0 1 1 1 1 0 1 ~ 0 1 0 1 0 1 1 0 ~ 1 1 1 1 0 0 1 0
0 0 1 0 1 1 1 0 1 0 1 0 0 0 1 0 1 1 0 1 0 1 0 0 ~ 1 0 1 0 1 0 0 ~ 0 1 1 1 1 0 1 1 ~ 1 1 0 0 1 0 0 0
1 1 1 1 0 1 0 1 1 0 1 0 0 0 1 0 ~ 0 0 1 1 0 1 0 1 ~ 1 1 0 1 0 0 0 ~ 1 1 1 0 0 0 0 0 ~ 1 1 0 0 0 0 1 1
0 1 1 1 0 1 0 0 0 1 0 0 1 1 0 0 ~ 1 0 1 0 0 0 1 0 ~ 1 1 1 0 0 1 0 ~ 0 0 1 0 1 0 1 0 ~ 1 1 1 1 0 1 0 1 ~
0 0 1 0 1 0 1 1 1 1 1 0 1 0 1 0 ~ 0 0 0 0 1 1 0 0 ~ 0 1 0 1 0 1 0 ~ 1 0 1 0 1 0 1 1 ~ 1 1 1 0 0 1 0 1 ~
01010001 01010100 11100001 0101011 11110101 11000010
11101000 11100010 00101110 1010100 11000000 10001011
```


## Physical Representation on the Computer



## Game Console

You cannot learn how to program in just one day. And anyway, we want to focus on high-level ideas, not on low-level nitty gritty.

All the low-level stuff is taken care of by the ToH Game Console, a Prolog program providing a few simple predicates ("commands") for you to manipulate the towers.

```
init(+N) create a game with N disks (with N }\in{1,2,3,4,\ldots}
move(+A,+B) move the top disk on peg A to B (A, B \in {1,2,3})
top(+A,-D) given peg A, return top disk D on A (if any)
empty(+A) check whether peg A is empty
```

Here '+' means that you provide a value and '-' means that you receive a value (by using a variable). Example:

$$
\begin{aligned}
& ?-\operatorname{top}(1, X) . \\
& X=3 .
\end{aligned}
$$

## First Solution

Focus on the case of 3 disks for now.
To solve the game, you have to move the top disk on peg 1 to peg 3, and then move the top disk on peg 1 to peg 2, and then move the top disk on peg 3 to peg 2, and then

In Prolog this is implemented as follows:

```
sillySolve :-
move(1,3), move(1,2), move(3,2), move(1,3),
move(2,1), move(2,3), move(1,3).
```

This will work. Type into Prolog (with the Game Console loaded):
?- init(3), sillySolve.

Good solution?

## Second Solution

What are the possible moves available at a given time?

- move disk 1 (the smallest disk) "to the right" [1R]
- move disk 1 (the smallest disk) "to the left" [1L]
- make the only possible move not involving disk 1 [N1] (note that N1 is not possible in the initial or final configuration)

Observations:

- never iterate $1 \mathrm{R} / 1 \mathrm{~L}$ (can achieve same effect with one move)
- never iterate N1 (amounts to undoing previous move)

Thus:

- should alternate $1 \mathrm{R} / 1 \mathrm{~L}$ with N 1

But which one, 1R or 1L? Leap of faith: let's just try with $1 R$.

## The Iterative Solution

To summarise, our algorithm is this:
(1) Perform 1R (move disk 1 to the right, from peg 1 to peg 2 ).
(2) Repeat until the final configuration is reached:
(a) Perform N1 (only possible move not involving disk 1 ).
(b) Perform 1R (move disk 1 one peg "to the right").

This works! (at least when the number $n$ of disks is even) If $n$ is odd, use 1 L instead of $1 R$.

This is pretty cool. But hard to understand why it actually works.

## The Iterative Solution in Prolog

This is not so easy to implement and we'll brush over some details.

```
move1R :- % to perform 1R:
    where(1,Peg), % find peg of disk 1
    right(Peg). % move disk 1 one peg to the right
moveN1 :- % to perform N1:
    where(1,Peg1), % find peg of disk 1
    whereOtherDisk(Peg2), % find peg of next smallest top disk
    getThirdPeg(Peg1,Peg2,Peg3), % find name of third peg
    move(Peg2, Peg3). % move second smallest disk to third peg
itSolve :- % to solve the game:
    move1R, finish. % perfom 1R, then finish off
finish :- empty(1), empty(2). % finished if: pegs 1 & 2 empty
finish :- % to finish:
    moveN1, move1R, finish. % perform N1, then 1R, then finish off
```


## Third Solution

Wanted: method to move a tower of $n$ disks from peg A to peg B.
Solution:
To move a tower of $n$ (with $n>1$ ) disks from A to B , simply
(1) move $n-1$ disks from A to C ,
(2) move the largest disk from $A$ to $B$, and
(3) move $n-1$ disks from C to B

For the case of a tower with just 1 disk, we know what to do.
This works. Magic?

## Two Auxiliary Predicates

We will need two auxiliary predicates that take care of some very basic stuff for us that is related to the manipulation of numbers. getPredecessor $(+N,-P)$ : Given a natural number $N$, return that number's predecessor $\mathrm{P}:=\mathrm{N}-1$. Example:

$$
\begin{aligned}
& ?-\text { getPredecessor }(10, X) . \\
& X=9 .
\end{aligned}
$$

getThirdPeg $(+\mathrm{A},+\mathrm{B},-\mathrm{C})$ : Given the names of pegs A and B , return that of the third peg C (names are 1, 2, and 3). Example:

```
?- getThirdPeg(3,1,X).
X = 2.
```

Btw, all that getThirdPeg/3 does is to compute $C:=6-(A+B)$.

## The Recursive Solution in Prolog

recSolve ( $\mathrm{N}, \mathrm{A}, \mathrm{B}$ ) implements our recursive algorithm to move a tower with N disks from location A to location B :

```
recSolve(N, A, B) :- % to move a tower from A to B
        N =:= 1,
        move(A, B).
recSolve(N, A, B) :- % to move a tower from A to B
    N > 1,
    getPredecessor(N, N1), % get predecessor N1 of N
    getThirdPeg(A, B, C), % get name of third peg C
    recSolve(N1, A, C),
    move(A, B),
    recSolve(N1, C, B).
% if size N is equal to 1:
% move single disk from A to B
    % if size N is greater than 1:
    % move tower of size N-1 to C
    % move largest disk to B
    % move tower of size N-1 to B
```


## Complexity

How complex is the Towers of Hanoi problem? That is, how long does it take to solve a game with $n$ disks?

Answer: depends how fast you can move one disk
So better ask: how many steps to solve a game with $n$ disks?

- $n=1$ : ?
- $n=2$ : ?
- $n=3:$ ?


## Formal Complexity Analysis

Observations: You must move the largest disk (size $n$ ) eventually. You can only move it, if the remaining tower sits somewhere else. So our recursive algorithm is optimal:
(1) move tower of size $n-1$ out of the way
(2) move largest disk in place
(3) move tower of size $n-1$ on top of it

Let $f(k)$ be the number of steps needed for a game with $k$ disks.
We know $f(1)=1$ (solving a game with 1 disk takes 1 step).
From our algorithm, for a game with $n$ disks we immediately get:

$$
f(n)=f(n-1)+1+f(n-1)=2 \cdot f(n-1)+1
$$

Not yet helpful for computing, say, $f(10)$. We want a closed form .

## Closed Form

What is $f(n)$, the number of steps to solve a game with $n$ disks?
We have established:

- $f(1)=1$
- $f(n)=2 \cdot f(n-1)+1 \quad(*)$

Examples: $f(2)=3, f(3)=7, f(4)=15, f(5)=31, f(6)=63, \ldots$
What we really want:
Claim: $f(n)=2^{n}-1$ for every $n \in \mathbb{N}$.
Proof: Take any $n>1$. Suppose for a moment that the claim were true for $n-1$, meaning that $f(n-1)=2^{n-1}-1 .(* *)$ But then:

$$
f(n) \stackrel{*}{=} 2 \cdot f(n-1)+1 \stackrel{* *}{=} 2 \cdot\left[2^{n-1}-1\right]+1=2^{n}-1
$$

The claim is true for $n=1$, as we have seen.
Thus, by induction, it must be true for every $n \in \mathbb{N}$. $\checkmark$

## Summary

What you've learned about today:

- several methods for solving Towers of Hanoi
- programming in Prolog (well, a bit)

What this really has been about:

- need to find the right representation of a problem
- need to abstract away from low-level details
- importance of striving for general solutions
- importance of formal/mathematical analysis of solutions


## What next?

- grab a copy of the handout on your way out (to have lunch)
- if not done yet, install SWI-Prolog on your laptop
- be at one of the lab rooms at 14:00 for the practicum
- submit your assignment by 17:00 today

