

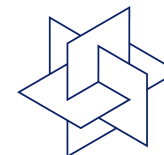


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Finance Winterschool 2007, Lunteren NL

Policy iterated lower bounds and linear MC upper bounds for Bermudan style derivatives

Pricing complex structured products



DFG Research Center MATHEON
Mathematics for key technologies

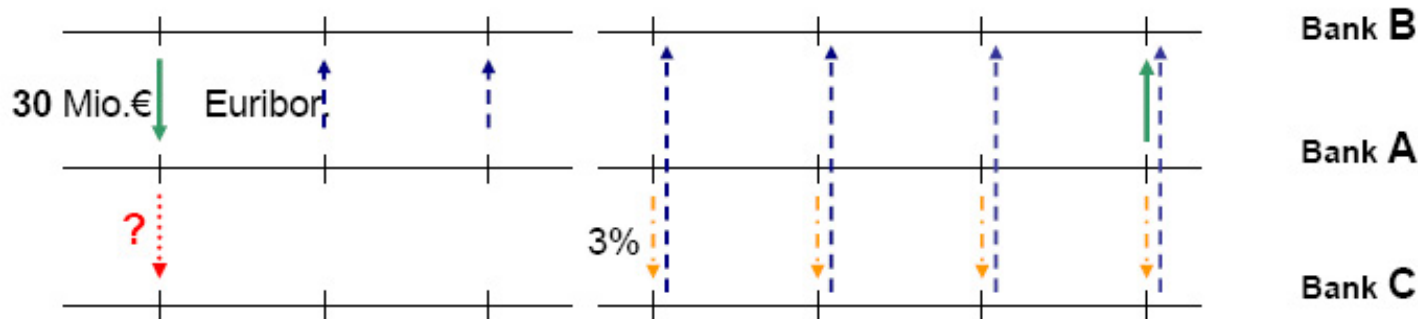
Bermudan callable products

Simple example: (Bermudan) callable interest rate swap

Euribor: Interest rate for a loan between banks

Contract I: A borrows from B 30 Mio. € over a period of 10 years and pays quarterly the 3M-Euribor.

Contract II: A buys from C a Bermudan swaption, i.e. the right to choose a payment date of contract I, from which on C pays quarterly the 3M-Euribor to B and receives a fixed payment of 3% from A.



'Exotic' example: cancelable snowball swap

Snowball swap: Instead of the **floating spot rate** the holder pays a starting coupon rate **I** over the first year and in the forthcoming years

$$(\mathbf{K} + \text{previous coupon} - \text{spot rate})^+,$$

where the first coupon **I** and the strike rate **K** are specified in the contract.

Cancelable snowball swap: The holder has the right to **cancel** this contract.

What is the fair value of this cancelable product?

▷ **Mathematical problem:**

Optimal stopping (calling) of a reward (cash-flow) process Z depending on an underlying (e.g. interest rate) process L

▷ **Typical difficulties:**

- L is usually **high dimensional**, for Libor interest rate models, $d = 10$ and up, so PDE methods do not work in general
- Z may only be virtually known, e.g. $Z_i = E^{\mathcal{F}_i} \sum_{j \geq i} C(L_j)$ for some pay-off function C , rather than simply $Z_i = C(L_i)$
- Z may be **path-dependent**

The standard Bermudan pricing problem

Consider an underlying process L in \mathbb{R}^D , e.g. a system of asset prices or Libor rates and a set of (future) dates $\mathbb{T} := \{\mathcal{T}_0, \mathcal{T}_1, \dots, \mathcal{T}_k\}$

Bermudan derivative: An option to exercise a cashflow $C(\mathcal{T}_\tau, L(\mathcal{T}_\tau))$ at a future time $\mathcal{T}_\tau \in \mathbb{T}$, to be decided by the option holder

Valuation: If N , with $N(0) = 1$, is some discounting numeraire and P the with N associated pricing measure, then with $Z_\tau := C(\mathcal{T}_\tau, L(\mathcal{T}_\tau))/N(\mathcal{T}_\tau)$, the $t = 0$ price of the option is given by the **optimal stopping problem**

$$V_0 = \sup_{\tau \in \{0, \dots, k\}} E^{\mathcal{F}_0} Z^{(\tau)},$$

where the supremum runs over all stopping indexes τ with respect to $\{\mathcal{F}_{\mathcal{T}_i}, 0 \leq i \leq k\}$, where $(\mathcal{F}_t)_{t \geq 0}$ is the usual filtration generated by L .

At a future time point t , when the option is not exercised before t , the Bermudan option value is given by

$$V_t = N(t) \sup_{\tau \in \{\kappa(t), \dots, k\}} E^{\mathcal{F}_t} Z(\tau)$$

with $\kappa(t) := \min\{m : \mathcal{T}_m \geq t\}$.

The process

$$Y_t^* := \frac{V_t}{N(t)},$$

called the *Snell-envelope* process, is a supermartingale, i.e.

$$E^{\mathcal{F}_s} Y_t^* \leq Y_s^*$$

Canonical Solution by Backward Dynamic Programming

Set $Y^{*(i)} := Y^*(\mathcal{T}_i)$, $\mathcal{F}^{(i)} := \mathcal{F}_{\mathcal{T}_i}$. At the last exercise date \mathcal{T}_k we have,

$$Y^{*(k)} = Z^{(k)}$$

and for $0 \leq j < k$,

$$Y^{*(j)} = \max \left(Z^{(j)}, E^{\mathcal{F}_j} Y^{*(j+1)} \right).$$

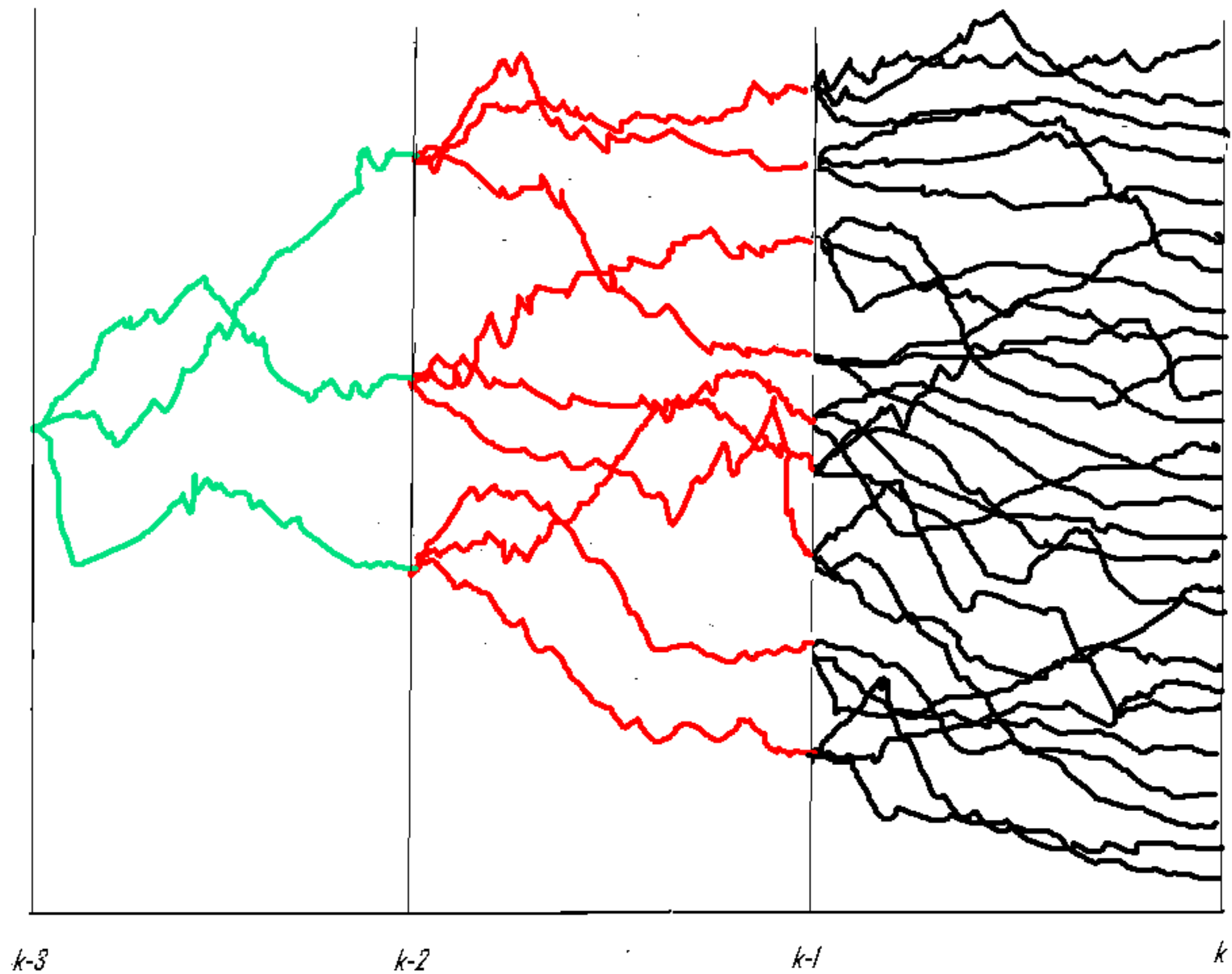
The first optimal stopping time (index) is then obtained by

$$\tau_i^* = \inf \left\{ j, i \leq j \leq k : Y^{*(j)} \leq Z^{(j)} \right\}.$$

→ Nested Monte Carlo simulation of the price Y_0^* would thus require N^k samples when conditional expectations are computed with N samples

Typically, $N=10000$, $k=10$ exercise opportunities, give 10^{40} samples !!

Optimal stopping



New approaches:

- I A path-by-path **policy iteration methodology** to improve upon standard methods (e.g. Longstaff-Schwartz, Piterbarg, Andersen)
- II Application to **complex exotic structures**
- III A **linear Monte Carlo algorithm for price upper bounds** via regression estimators of Doob martingale parts

Iterative construction of the optimal stopping time

References:

Kolodko, A., Schoenmakers, J. (2006) Iterative construction of the optimal Bermudan stopping time. *Finance and Stochastics*, **10**(1), 27-49

Part I: Iterative construction of the optimal stopping time

Improving upon given input stopping policies

We consider an input stopping family (policy) (τ_i) , which satisfies the consistency conditions:

$$i \leq \tau_i \leq k, \quad \tau_k = k, \quad \tau_i > i \Rightarrow \tau_i = \tau_{i+1}, \quad 0 \leq i < k,$$

and the corresponding lower bound process Y for the Snell envelope Y^* ,

$$Y^{(i)} := E^{\mathcal{F}^{(i)}} Z^{(\tau_i)} \leq Y^{*(i)}$$

Example input policies:

- ▷ The policy, $\tau_i \equiv i$. says: **exercise immediately!**
- ▷ The policy $\tau_i := \inf\{j \geq i : L(\mathcal{T}_j) \in G \subset \mathbb{R}^D\}$ exercises when **the underlying process L enters a certain region G**
- ▷ The policy $\tau_i = \inf\{j : i \leq j \leq k, \max_{p: j \leq p \leq k} E^{\mathcal{F}^{(j)}} Z^{(p)} \leq Z^{(j)}\}$ waits **until the cashflow is at least equal to the maximum of still-alive Europeans ahead**

Part I: Iterative construction of the optimal stopping time

One step improvement:

Introduce an intermediate process

$$\tilde{Y}^{(i)} := \max_{p: i \leq p \leq k} E^{\mathcal{F}^{(i)}} Z^{(\tau_p)}$$

and use $\tilde{Y}^{(i)}$ as a new exercise criterion to define a new exercise policy

$$\begin{aligned} \hat{\tau}_i &:= \inf\{j : i \leq j \leq k, Z^{(j)} \geq \tilde{Y}^{(j)}\} \\ &= \inf\{j : i \leq j \leq k, Z^{(j)} \geq \max_{p: j \leq p \leq k} E^{\mathcal{F}^{(j)}} Z^{(\tau_p)}\}, \quad 0 \leq i \leq k \end{aligned}$$

Then consider the process

$$\hat{Y}^{(i)} := E^{\mathcal{F}^{(i)}} Z^{(\hat{\tau}_i)}$$

as a next approximation of the Snell envelope

Key Proposition It holds

$$Y^{(i)} \leq \tilde{Y}^{(i)} \leq \hat{Y}^{(i)} \leq Y^{*(i)}, \quad 0 \leq i \leq k$$

Part I: Iterative construction of the optimal stopping time

Iterative construction of the optimal stopping time

Take an initial family of stopping times $(\tau_i^{(0)})$ satisfying the consistency conditions

$$i \leq \tau_i^{(0)} \leq k, \quad \tau_k^{(0)} = k, \quad \tau_i > i \Rightarrow \tau_i = \tau_{i+1},$$

and set $Y^{0(i)} := E^{\mathcal{F}^{(i)}} Z(\tau_i^{(0)})$, $0 \leq i \leq k$. Suppose that for $m \geq 0$ the pair

$$\left((\tau_i^{(m)}), (Y^{m(i)}) \right)$$

is constructed with $\tau_i^{(m)}$ being consistent and $Y^{m(i)} := E^{\mathcal{F}_i} Z(\tau_i^{(m)})$, $0 \leq i \leq k$. Then define

$$\begin{aligned} \tau_i^{(m+1)} &:= \inf \left\{ j : i \leq j \leq k, \max_{p: j \leq p \leq k} E^{\mathcal{F}^{(j)}} Z(\tau_p^{(m)}) \leq Z^{(j)} \right\} \\ &=: \inf \left\{ j : i \leq j \leq k, \tilde{Y}^{m+1}(j) \leq Z^{(j)} \right\}, \quad 0 \leq i \leq k, \end{aligned}$$

and set

$$Y^{m+1(i)} := E^{\mathcal{F}^{(i)}} Z(\tau_i^{(m+1)})$$

Part I: Iterative construction of the optimal stopping time

By the 'key proposition' we thus have

$$Y^{0(i)} \leq Y^{m(i)} \leq \tilde{Y}^{m+1(i)} \leq Y^{m+1(i)} \leq Y^{*(i)}, \quad 0 \leq m < \infty, \quad 0 \leq i \leq k.$$

and it is shown that for $m \geq 1$,

$$\tau_i^{(m)} \leq \tau_i^{(m+1)} \leq \tau_i^*,$$

where τ_i^* is the first optimal stopping time.

We so may take limits and it holds,

$$Y^\infty(i) := (\text{a.s.}) \lim_{m \uparrow \infty} \uparrow Y^{m(i)} \quad \text{and} \quad \tau_i^\infty := (\text{a.s.}) \lim_{m \uparrow \infty} \uparrow \tau_i^{(m)}, \quad 0 \leq i \leq k, \quad \text{and,}$$

$$Y^\infty(i) = (\text{a.s.}) \lim_{m \uparrow \infty} \uparrow E^{\mathcal{F}^{(i)}} Z(\tau_i^{(m)}) = E^{\mathcal{F}^{(i)}} Z(\tau_i^\infty), \quad 0 \leq i \leq k$$

Theorem

The constructed limit process Y^∞ coincides with the Snell envelope process Y^* and (τ_i^∞) coincides with (τ_i^*) ; the family of first optimal stopping times. We have

$$Y^{*(i)} = Y^{\infty(i)} = E^{\mathcal{F}^{(i)}} Z^{(\tau_i^\infty)}, \quad 0 \leq i \leq k.$$

Moreover: It even holds

$$Y^{m(i)} = Y^{*(i)} \quad \text{for} \quad m \geq k - i$$

→ After $k = \#$ exercise dates iterations the Snell Envelope is attained!

Part I: Iterative construction of the optimal stopping time

Iteration procedure vs backward dynamic program

		— Exercise date →					
		0	1	...	$k-2$	$k-1$	k
Iteration level ↓	0	$Y_0^{(0)}$	$Y_1^{(0)}$...	$Y_{k-2}^{(0)}$	$Y_{k-1}^{(0)}$	Y_k^*
	1	$Y_0^{(1)}$	$Y_1^{(1)}$...	$Y_{k-2}^{(1)}$	Y_{k-1}^*	Y_k^*
	2	$Y_0^{(2)}$	$Y_1^{(2)}$		Y_{k-2}^*	Y_{k-1}^*	Y_k^*

	$k-1$	$Y_0^{(k-1)}$	Y_1^*	...	Y_{k-2}^*	Y_{k-1}^*	Y_k^*
	k	Y_0^*	Y_1^*	...	Y_{k-2}^*	Y_{k-1}^*	Y_k^*

Upper approximations of the Snell envelope by Duality

The Dual Method

Consider a discrete martingale $(M_j)_{j=0,\dots,k}$ with $M_0 = 0$ with respect to the filtration $(\mathcal{F}^{(j)})_{j=0,\dots,k}$. Following Rogers, Haugh and Kogan, we observe that

$$\begin{aligned} Y_0 &= \sup_{\tau \in \{0,\dots,k\}} E^{\mathcal{F}_0} Z^{(\tau)} = \sup_{\tau \in \{0,\dots,k\}} E^{\mathcal{F}_0} [Z^{(\tau)} - M_\tau] \\ &\leq E^{\mathcal{F}_0} \max_{0 \leq j \leq k} [Z^{(j)} - M_j] \end{aligned}$$

Hence the r.h.s. gives an upper bound for the Bermudan price $V_0 = Y_0$.

Theorem (Davis Karatzas (1994), Rogers (2001), Haugh & Kogan (2001))

Let M^* be the (unique) Doob-Meyer martingale part of $(Y^{*(j)})_{0 \leq j \leq k}$, i.e. M^* is an $(\mathcal{F}^{(j)})$ -martingale which satisfies

$$Y^{*(j)} = Y_0^* + M_j^* - F_j^*, \quad j = 0, \dots, k,$$

with $M_0^* := F_0^* := 0$ and F^* being such that F_j^* is $\mathcal{F}^{(j-1)}$ measurable for $j = 1, \dots, k$. Then we have

$$Y_0^* = E^{\mathcal{F}_0} \max_{0 \leq j \leq k} [Z^{(j)} - M_j^*].$$

Part I: Converging upper bounds

Convergent upper bounds from a convergent sequence of lower bounds

From our previously constructed sequence of lower bound processes $Y^{m(i)}$ with $Y^{m(i)} \uparrow Y^*(i)$, we deduce **by duality** a sequence of upper bound processes:

$$Y_{up}^{m(i)} := E^{\mathcal{F}_i} \max_{i \leq j \leq k} \left(Z^{(j)} - \sum_{l=i+1}^j Y^{m(l)} + \sum_{l=i+1}^j E^{\mathcal{F}^{(l-1)}} Y^{m(l)} \right) =: Y^{m(i)} + \Delta^{m(i)}.$$

Then, by a theorem of (Kolodko & Schoenmakers 2004),

$$0 \leq \Delta^{m(i)} \leq E^{\mathcal{F}_i} \sum_{j=i}^{k-1} \max \left(E^{\mathcal{F}_j} Y^{m(j+1)} - Y^{m(j)}, 0 \right).$$

Thus, by letting $m \uparrow \infty$ on the r.h.s., (a.s.) $\lim_{m \rightarrow \infty} \Delta^{m(i)} = 0$, $0 \leq i \leq k$. Hence, the sequence Y_{up}^m **converges to the Snell envelope also**, i.e.,

$$(\text{a.s.}) \lim_{m \rightarrow \infty} Y_{up}^{m(i)} = (\text{a.s.}) \lim_{m \rightarrow \infty} Y^{m(i)} = Y^*(i), \quad 0 \leq i \leq k.$$

Part I: Application: Bermudan swaptions

A first numerical example: Bermudan swaptions in the LIBOR market model

Consider the Libor Market Model with respect to a tenor structure $0 < T_1 < T_2 < \dots < T_n$, e.g. in the spot Libor measure P^* induced by the numeraire

$$B^*(t) := \frac{B_{m(t)}(t)}{B_1(0)} \prod_{i=0}^{m(t)-1} (1 + \delta_i L_i(T_i))$$

with $m(t) := \min\{m : T_m \geq t\}$.

The dynamics of the forward Libor $L_i(t)$ is given by a system of SDE's

$$dL_i = \sum_{j=m(t)}^i \frac{\delta_j L_i L_j \gamma_i \cdot \gamma_j}{1 + \delta_j L_j} dt + L_i \gamma_i \cdot dW^*.$$

Here $\delta_i = T_{i+1} - T_i$ are day count fractions, and

$$t \rightarrow \gamma_i(t) = (\gamma_{i,1}(t), \dots, \gamma_{i,d}(t))$$

are deterministic volatility vector functions defined in $[0, T_i]$, called factor loadings.

A (payer) Swaption over a period $[T_i, T_n]$, $1 \leq i \leq k$. A swaption contract with maturity T_i and strike θ with principal \$1 gives the right to contract at T_i for paying a fixed coupon θ and receiving floating Libor at the settlement dates T_{i+1}, \dots, T_n . So by this definition, its cashflow at maturity is

$$S_{i,n}(T_i) := \left(\sum_{j=i}^{n-1} B_{j+1}(T_i) \delta_j (L_j(T_i) - \theta) \right)^+.$$

A Bermudan Swaption gives the the right to exercise a cashflow

$$C_{T_\tau} := S_{\tau,n}(T_\tau)$$

at an exercise date $T_\tau \in \{T_1, \dots, T_n\}$ to be decided by the option holder.

Part I: Application: Bermudan swaptions

10 yr. Bermudan swaption: (20 underlying LIBORS)

Comparison of Y^1 , Y^2 , $Y^{1,up}$, where $\tau_i^{(0)} \equiv i$ (trivial initial stopping family)

θ	d	Y^1 (SD)	Y^2 (SD)	$Y^{1,up}$ (SD)
0.08 (ITM)	1	1104.6(0.5)	1108.9(2.4)	1109.4(0.7)
	2	1098.6(0.4)	1100.5(2.4)	1103.7(0.7)
	10	1094.4(0.4)	1096.9(2.1)	1098.1(0.6)
	40	1093.6(0.4)	1096.1(2.0)	1096.6(0.6)
0.10 (ATM)	1	374.3(0.4)	381.2(1.6)	382.9(0.8)
	2	357.9(0.3)	364.4(1.5)	366.4(0.8)
	10	337.8(0.3)	343.5(1.3)	345.6(0.7)
	40	332.6(0.3)	338.7(1.2)	341.2(0.8)
0.12 (OTM)	1	119.0(0.2)	121.0(0.6)	121.3(0.4)
	2	112.7(0.2)	113.8(0.5)	114.9(0.4)
	10	100.2(0.2)	100.7(0.4)	101.5(0.3)
	40	96.5(0.2)	96.9(0.4)	97.7(0.3)

Conclusions from the tables:

- ▷ The computed lower bound Y^2 , hence the second iteration, is within 1% or less (relative to the price) of the Dual upper bound $Y^{1,up}$
- ▷ Computation times (order of minutes) may be considered low in view of the high-dimensionality of the problem!

Some more general remarks

- ▷ The iterative approach provides a general method for **improving upon any given input stopping policy** obtained by other means (e.g. Andersen, Longstaff-Schwartz)
- ▷ Computation times may be reduced further by a **scenario selection method** by Bender, Kolodko, Schoenmakers

Pricing of path-dependent cancellables

References:

C. Bender, A. Kolodko, and J. Schoenmakers. Iterating cancellable snowballs and related exotics. *Risk*, pages 126-130, September 2006.

Part II: Exotic products

Consider a **path dependent cancelable contract** which generates (possibly negative) cash-flows

$$C_1, \dots, C_\tau$$

up to a cancellation date τ . The cash-flows of this contract are equivalent to an aggregated cash-flow at cancellation date,

$$B_*(\mathcal{I}_\tau) \mathcal{Z}_\tau := B_*(\mathcal{I}_\tau) \sum_{j=1}^{\tau} Z_j,$$

with $Z_i := C_i / B_*(\mathcal{I}_i)$ being discounted cash-flows with respect to the numeraire B_* . Product price at time zero:

$$V_0^{cancel} := \sup_{\tau \in \{1, \dots, k\}} E^{\mathcal{F}_0} \mathcal{Z}_\tau = \sup_{\tau \in \{1, \dots, k\}} E^{\mathcal{F}_0} \sum_{j=1}^{\tau} Z_j,$$

where the supremum is taken over all stopping indices with values in the set $\{1, \dots, k\}$.

Path-dependent callables

A path dependent **callable** contract generates

$$C_{\tau+1}, \dots, C_k$$

when called at τ . It is equivalent to the sum of a non-callable and a cancelable one (and vice versa):

$$\begin{aligned} V_0^{call} &:= \sup_{\tau \in \{1, \dots, k\}} E^{\mathcal{F}_0} \sum_{j=\tau+1}^k Z_j \\ &= E^{\mathcal{F}_0} \sum_{j=1}^k Z_j + \sup_{\tau \in \{1, \dots, k\}} E^{\mathcal{F}_0} \sum_{j=1}^{\tau} (-Z_j) \end{aligned}$$

Example: The cancelable snowball swap

Pays semi-annually a constant rate I over the first year and in the forthcoming years $(\text{Previous coupon} + A - \text{Libor})^+$, semi-annually, where A is given in the contract. For this case we take

$$\begin{aligned}K_i &:= I, \quad i = 0, 1, \\K_i &:= (K_{i-1} + A_i - L_i(T_i))^+, \quad i = 2, \dots, n - 1,\end{aligned}$$

with $A_2 := 0.03$, $A_{i+1} = A_i$ for even i , $A_{i+1} = A_i + 0.005$ for odd i . Cancellation is allowed for $2 \leq \tau < n$, $n = 20$ (10 years)

Effective discounted cashflows at T_j :

$$Z_j := \frac{(L_{j-1}(T_{j-1}) - K_{j-1}) \delta_{j-1}}{B_*(T_j)},$$

hence aggregated up to cancellation $Z_\tau = \sum_{j=1}^{\tau} Z_j$.

Iterating the snowball swap

Take an input policy satisfying

$$\begin{aligned} i &\leq \tau_i \leq k, \quad \tau_k = k, \\ \tau_i > i &\Rightarrow \tau_i = \tau_{i+1}, \quad 0 \leq i < k, \end{aligned}$$

construct the new policy

$$\begin{aligned} \hat{\tau}_i &:= \inf\{j \geq i : Z_j \geq \max_{p: j \leq p \leq k} E^{\mathcal{F}_j} Z_{\tau_p}\} \\ &= \inf\{j \geq i : 0 \geq \max_{p: j \leq p \leq k} E^{\mathcal{F}_j} \sum_{q=j+1}^{\tau_p} Z_q\} \end{aligned}$$

and compute the iterated price

$$\hat{Y}_0 := E^{\mathcal{F}_0} Z_{\hat{\tau}_0},$$

which is generally an improvement of Y_0 due to policy τ .

Numerical results for typical market data

Improved Andersen

d	$Y(0; \tau_A)$ (SD)	$\hat{Y}(0; \tau_A)$ (SD)	$Y_{up}(0; \tau_A)$ (SD)
1	127.77(0.238)	129.77(0.318)	130.33(0.247)
2	114.93(0.231)	120.00(0.389)	121.92(0.293)
19	76.725(0.217)	91.600(0.460)	98.107(0.476)

150 000 outer and 500 inner paths for \hat{Y} and 20 000 outer (with 500 inner) paths for Y_{up} .

Improved least-squares regression method (Piterbarg)

d	$Y(0; \tau_{LS})$ (SD)	$\hat{Y}(0; \tau_{LS})$ (SD)	$Y_{up}(0; \tau_{LS})$ (SD)
1	117.73(0.243)	128.81(0.632)	132.28(0.313)
2	103.70(0.238)	120.73(0.466)	123.54(0.346)
19	74.913(0.224)	93.515(0.469)	97.479(0.379)

200 000 outer and 500 inner paths for \hat{Y} and 20 000 outer (with 500 inner) paths for Y_{up} .

Improving an Andersen-like optimization of the LS exercise boundary

d	$Y(0; \tau_{LS-A})$ (SD)	$\hat{Y}(0; \tau_{LS-A})$ (SD)	$Y_{up}(0; \tau_{LS-A})$ (SD)
1	129.58(0.237)	128.70(0.349)	130.24(0.244)
2	119.58(0.230)	118.95(0.345)	120.77(0.244)
10	92.201(0.219)	97.376(0.456)	100.20(0.418)
19	87.787(0.217)	94.487(0.445)	95.843(0.430)

150 000 outer and 100 inner paths for \hat{Y} and 5000 outer (with 500 inner) paths for Y_{up} .

$$\tau_{LS-A, i} = \inf\{j \geq i : Z_j \geq H_j + Y_{LS, j}\}$$

with optimized constants H_j .

Message:

- (i) Price the callable using Pitterbarg's version of Longstaff-Schwartz;
- (ii) Improve the obtained exercise boundary with an Andersen-like optimization;
- (iii) Compute the Dual upperbound due to the stopping time $\tau_{LS-A, 0}$;
- (iv) If there is still a significant gap between lower and upper bound, then improve the policy $\tau_{LS-A, i}$ by the iteration method.

True upper bounds via non-nested Monte Carlo

Joint work with D. Belomestny and C. Bender

For any martingale M_{T_j} , $0 \leq j \leq k$ with respect to the filtration $(\mathcal{F}_{T_j}; 0 \leq j \leq k)$ starting at $M_0 = 0$

$$Y_0^{up}(M) := E^{\mathcal{F}_0} \left[\max_{0 \leq j \leq k} (Z_{T_j} - M_{T_j}) \right]$$

is an upper bound for the price of the Bermudan option with discounted cash-flow Z_{T_j} .

Exact Bermudan price is attained at the martingale part M^* of the Snell envelope,

$$Y_{T_j}^* = Y_{T_0}^* + M_{T_j}^* + F_{T_j}^*,$$

$M_{T_0}^* = F_{T_0}^* = 0$ and $F_{T_j}^*$ is $\mathcal{F}_{T_{j-1}}$ measurable

Part III: Fast upper bounds

(I) Assume the underlying process L to be Markovian, and the filtration \mathcal{F} to be generated by a d -dimensional Brownian motion W .

(II) Assume $Y_{T_j} = u(T_j, L(T_j))$ is some approximation of the Snell envelope $Y_{T_j}^*$, $0 \leq j \leq k$, with Doob decomposition

$$Y_{T_j} = Y_{T_0} + M_{T_j} + F_{T_j},$$

$M_{T_0} = F_{T_0} = 0$ and F_{T_j} is $\mathcal{F}_{T_{j-1}}$ measurable.

It then holds:

$$\begin{aligned} Y_{T_{j+1}} - Y_{T_j} &= M_{T_{j+1}} - M_{T_j} + F_{T_{j+1}} - F_{T_j} \\ M_{T_{j+1}} - M_{T_j} &= Y_{T_{j+1}} - E^{T_j}[Y_{T_{j+1}}], \end{aligned}$$

with

$$M_{T_j} =: \int_0^{T_j} H_t dW_t =: \int_0^{T_j} \mathfrak{h}(t, L(t)) dW_t, \quad j = 0, \dots, k.$$

Part III: Fast upper bounds

We are going to estimate $\mathfrak{h}(\cdot, \cdot)$ (hence H) at the finite partition $\pi = \{t_0, \dots, t_{\mathcal{I}}\}$ such that $t_0 = 0$, $t_{\mathcal{I}} = T$, and $\{T_0, \dots, T_k\} \subset \pi$. We may write formally,

$$Y_{T_{j+1}} - Y_{T_j} \approx \sum_{t_l \in \pi; T_j \leq t_l < T_{j+1}} H_{t_l} (W_{t_{l+1}} - W_{t_l}) + F_{T_{j+1}} - F_{T_j}.$$

By multiplying both sides with $(W_{t_{i+1}}^d - W_{t_i}^d)$, $T_j \leq t_i < T_{j+1}$, and taking \mathcal{F}_{t_i} -conditional expectations, we get by the $\mathcal{F}_{T_{j+1}}$ -measurability of F_{T_j} ,

$$H_{t_i}^d \approx \frac{1}{t_{i+1} - t_i} E^{\mathcal{F}_{t_i}} \left[(W_{t_{i+1}}^d - W_{t_i}^d) Y_{T_{j+1}} \right],$$

and so define

$$H_{t_i}^\pi := \frac{1}{\Delta_i^\pi} E^{\mathcal{F}_{t_i}} \left[(\Delta_i^\pi W_i)^{\top} Y_{T_{j+1}} \right], \quad T_j \leq t_i < T_{j+1},$$

with $\Delta_i^\pi := t_{i+1} - t_i$ and $\Delta_i^\pi W_i^d := W_{t_{i+1}}^d - W_{t_i}^d$.

The corresponding approximation of the martingale M is

$$M_{T_j}^\pi := \sum_{t_i \in \pi; 0 \leq t_i < T_j} H_{t_i}^\pi(\Delta^\pi W_i).$$

Theorem:

$$\lim_{|\pi| \rightarrow 0} E \left[\max_{0 \leq j \leq k} |M_{T_j}^\pi - M_{T_j}|^2 \right] = 0$$

where $|\pi|$ denotes the mesh of π .

Part III: Fast upper bounds

The conditional expectations in the definition of H^π are, in fact, functions of $L(t_i)$. Precisely,

$$H_{t_i}^\pi = \mathfrak{h}^\pi(t, L(t_i)) = \frac{1}{\Delta_i^\pi} E^{(t_i, L(t_i))} [(\Delta^\pi W_i)^\top u(T_{j+1}, L(T_{j+1}))], \quad T_j \leq t_i < T_{j+1}.$$

which may be computed by **regression**: Take basis functions

$$\psi(t_i, \cdot) = (\psi_r(t_i, \cdot), r = 1, \dots, R)$$

and N independent samples $(t_i, {}_n L(t_i))$, $n = 1, \dots, N$ of $L(t_i)$ constructed from the Brownian increments $\Delta_n^\pi W_i$, $n = 1, \dots, N$.

Construct the regression matrix

$$A_{t_i}^\oplus := (A_{t_i}^\top A_{t_i})^{-1} A_{t_i}^\top,$$

where

$$A_{t_i} = (\psi_r(t_i, {}_n L(t_i)))_{n=1, \dots, N, r=1, \dots, R}$$

Result:

$$\begin{aligned}\widehat{\mathbf{h}}^\pi(t_i, x) &= \psi(t_i, x) A_{t_i}^\oplus \left(\frac{\Delta^\pi W_i}{\Delta_i^\pi} \cdot Y_{T_{j+1}} \right), \quad T_j \leq t_i < T_{j+1} \\ &=: \psi(t_i, x) \widehat{\beta}_{t_i},\end{aligned}$$

where

$$\left(\frac{\Delta^\pi W_i}{\Delta_i^\pi} \cdot Y_{T_{j+1}} \right) = \left(\frac{\Delta_n^\pi W_i^d}{\Delta_i^\pi} \cdot {}_n Y_{T_{j+1}} \right)_{n=1, \dots, N, d=1, \dots, D},$$

${}_n \widetilde{Y}_{T_{j+1}} := u(T_{j+1}, {}_n L(T_{j+1}))$, and $\widehat{\beta}_{t_i}$ is the $R \times D$ matrix of estimated regression coefficients at time t_i .

True linear Monte Carlo upperbound:

$$\widehat{Y}^{up}(\widehat{M}^\pi) = \frac{1}{\widetilde{N}} \sum_{n=1}^{\widetilde{N}} \max_{0 \leq j \leq k} \left[z(T_j, {}_n\widetilde{L}(T_j)) - \underbrace{\sum_{t_i \in \pi; 0 \leq t_i < T_j} \widehat{h}^\pi(t_i, {}_n\widetilde{L}(T_j)) (\Delta^\pi \widetilde{W}_i)}_{(*)} \right],$$

by doing a **new** simulation ${}_n\widetilde{L}(T_j)$, $\Delta_n^\pi \widetilde{W}_i$ $n = 1, \dots, \widetilde{N}$.

(*) is always a martingale, so the upper bound is **true!**

Part III: Numerical example: Max Call on D assets

Black-Scholes model:

$$dX_t^d = (r - \delta)X_t^d dt + \sigma X_t^d dW_t^d, \quad d = 1, \dots, D,$$

Pay-off:

$$Z_t := z(X_t) := (\max(X_t^1, \dots, X_t^D) - \kappa)^+.$$

$T_k = 3\text{yr}$, $k = 9$ (ex. dates), $\kappa = 100$, $r = 0.05$, $\sigma = 0.2$, $\delta = 0.1$, different D and x_0

D	x_0	Lower Bound Y_0	Upper Bound $Y_0^{up}(\widehat{M}^\pi)$	Upper Bound $Y_{10^4,200}^{up}(0)$	Upper Bound $Y_{10^4,50}^{up}(0)$
2	90	7.9751±0.139	8.6963±0.052	8.231	8.70±0.06
	100	13.883±0.177	14.515±0.073	14.18	14.43±0.07
	110	21.291±0.205	21.972±0.095	21.68	22.00±0.11
5	90	16.523±0.194	18.134±0.069	17.46	18.21±0.06
	100	26.042±0.232	27.976±0.085	27.33	28.05±0.09
	110	36.526±0.263	38.882±0.098	38.27	39.0±0.12

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